## APPLICATION OF MICROFLUIDIC DEVICES FOR THE STUDY OF BACTERIAL CHEMOTAXIS TO NAPL COMPONENTS IN POROUS MEDIA

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#### ABSTRACT

Nonaqueous phase liquid (NAPLs) contaminants are difficult to eliminate from the groundwater system due to their low solubility, low intrinsic reactivity and low release rates from soil or sediments. In situ bioremediation is an economical method to deal with NAPL pollution, but its efficiency is hindered due to the heterogeneous structure in soil. Chemotaxis, the microbial property by which microorganisms sense the concentration gradient of chemicals and migrate towards the preferential regions for their survival and growth, may be a key factor to achieve more efficient bioremediation. A heterogeneous microfluidic device (H-µChip) was designed to mimic features of the natural contaminated groundwater system, with NAPL contaminant trapped in designated locations within the low permeable region. Chemotaxis facilitated the bacteria (P. putida F1) to accumulate adjacent to the contaminated low permeable region as well as in vicinity of the NAPL contaminant sources. Chemotactic bacteria were also more difficult to be washed out from the contaminated region due to their interaction with attractant gradient. Bacteria in the device were also subjected to different flow rates within typical range of groundwater flow rates. A higher flow rate reduced the apparent effect of chemotaxis.

Another microfluidic device was fabricated that created a convection free channel (CF- $\mu$ Chip), in order to measure the two essential chemotaxis parameters: chemotactic sensitivity coefficient  $\chi_0$  and chemotactic receptor constant  $K_c$ . These two parameters are the key to quantifying the impact of chemotaxis; however, their values for *P. putida* F1 and toluene were not previously measured. This device provided a way to enhance the

accuracy of the measurement to a great extent compared to conventional methods. By performing the experiment at two different values of the attractant concentration, the two chemotaxis parameters could be determined independently. Chemotactic bacteria exhibited a larger accumulation when the attractant concentration was closer to the correct value of  $K_c$ ; therefore,  $K_c$  could be determined first, and then  $\chi_0$  could be easily derived after fitting the chemotactic patterns with the correct  $K_c$  in the mathematical models. Both *Pseudomonas putida* and *Escherichia coli* strains were used, and the predicted chemotaxis parameters were consistent with the published results and the values derived from related work.

The numerical solution of mathematical models using COMSOL algorithms yielded outcomes that were consistent with the experimental results, and statistical analysis also supported the experimental comparisons. There is no direct observation on biodegradation, but because toluene is degradable by *P. putida* F1, the experimental observations of biased accumulation of chemotactic bacteria around the NAPL sources within the low permeable region is expected to lead to an increase of contaminant consumption, which can improve the efficiency of bioremediation.

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### LIST OF SYMBOLS

Symbol	Definition [Unit]
Arabic	
a	attractant concentration [moles/L <sup>3</sup> ]
b	bacterial density [moles/L <sup>3</sup> ]
С	species concentration [moles/L <sup>3</sup> ]
d	depth of channel [L]
D	diffusion coefficient $[L^2/T]$
Ι	light intensity in 8-bit images
$K_c$	chemotaxis receptor constant [moles/L <sup>3</sup> ]
Ν	flux [1/L <sup>2</sup> T]
p	pressure [P]
t	time [T]
$u_{avg}$	average velocity [L/T]
u	flow velocity vector [L/T]
$v_b$	individual bacterial swimming speed [L/T]
VCh	chemotactic velocity [L/T]
x	distance in x-direction [L]

Greek

$\chi_0$	chemotactic sensitivity coefficient $[L^2/T]$
λ	run length between tumbles [L]
$\mu_0$	bacterial random motility coefficient [L <sup>2</sup> /T]
μ	dynamic viscosity [P T]
$ au_r$	bacterial run time [T]
heta	turn angle between two successive bacterial runs
ρ	fluid density [M/L <sup>3</sup> ]
ε <sub>p</sub>	porosity
К <sub>br</sub>	permeability of the porous medium [L <sup>2</sup> ]

#### **1** INTRODUCTION

# CHAPTER 1

# INTRODUCTION

#### 1.1 Motivation

Nonaqueous phase liquids (NAPL) are the most common industrial contaminants in groundwater pollution (Knutson et al., 2001). NAPL contaminants, including BTEX (benzene, toluene, ethylbenzene, and xylenes), trichloroethylene (TCE), petroleum and chlorinated hydrocarbons (Newell et al., EPA), are difficult to eliminate from natural aquifers due to their low solubility, low volatility, low intrinsic reactivity and low release rates from soil or sediments (Pignatello and Xing, 1996; Ang et al., 2005). As a consequence, they have become a major threat to the groundwater sources for our daily usage.

Many remediation techniques and strategies are developed to eliminate this longterm threat. These methods include pump-and-treat, injection of catalytic metal particles, excavation, thermal desorption, air sparging and multi-phase extraction (Liu et al., 2005; Boopathy, 2000), and are generally high-cost and labor-intensive. The U. S. Environmental Protection Agency reported that over half billion kilowatt-hours (kWh) of energy was consumed for the most frequently applied remediation treatments at the National Priority List (NPL) sites every year (EPA, 2008), and the energy cost was predicted double in 2030. The induced economic and environmental burden behind the energy cost was something that could not be ignored. Therefore, a more economical alternative choice was needed.

In-situ bioremediation provides such an effective and economical solution to remove the organic pollutants from groundwater (Hart, 1996; Jorgensen, 2007; Scow et al., 2005). Generally speaking, indigenous microorganisms or other forms of biomass are injected into the contaminated sites and directly degrade or transform contaminant chemicals into non-toxic byproducts (Grindstaff, 1998); at the same time, microorganisms may grow and increase their population upon the contaminant sources, which can accelerate the biodegradation process. In-situ bioremediation quickly gained popularity among various treatment options, because it is cheaper and more effective than the conventional approaches.

However, in-situ bioremediation has its own limitations. Because of the heterogeneity of the natural groundwater systems, the NAPL contaminant sources are

easily trapped in regions where the conductivity is fairly low, either coating on the surface of soil grains or hiding in the narrow pore spaces (Figure 1.1). Thus, these NAPL residuals are hard to be carried away by the convective flow in adjacent zones with high hydraulic conductivity (Alexander, 1994; Harms and Wick, 2006; Gierczak et al., 2006). One prominent example is the oil spill from the tanker *Exxon Valdez* in 1989. Although soluble contaminants were removed from the high-permeability upper layer of the beach by conventional remediation, residual oil persists in the low-permeability lower layer, and continues to leach slowly into the upper layer (Li and Boufadel, 2010). Therefore, a more efficient method is needed to remediate the low permeable regions, in order to ensure complete removal of oil.



**Figure 1.1** Schematic illustration of NAPL contamination in soil (Courtesy from Soga et al., 2004).

Chemotaxis, the microbial property by which microorganisms sense the concentration gradient of chemicals and migrate towards the preferential regions for their

survival and growth, may be a key factor to achieve more efficient bioremediation (Pandey and Jain, 2002; Ford and Harvey, 2007). Chemotaxis phenomena were associated with the biodegradation of many environmental chemicals, including NAPL and various aromatic compounds; because of the ability to locate and degrade the pollutants, such bacteria have a selective advantage to survive and grow in various contaminated sites, and as a consequence, reduce the pollutants in these areas (Harms and Wick, 2006; Pandey and Jain, 2002; Harwood et al., 1984; Parales et al., 2000; Lopez-de-Victoria and Lovell, 1993; Grimm and Harwood, 1997; Law and Aitken, 2003; Harwood et al., 1990; Hawkins and Harwood, 2002; Bhushan et al., 2000; Samanta et al., 2000). An indigenous bacterial strain *P. putida* F1 was studied, because it showed strong chemotactic responses to and degraded many chlorinated hydrocarbons, such as toluene, benzene, trichloroethylene etc. (Harwood et al., 1990; Parales et al., 2000), and was widely applied to study bacterial chemotaxis. In this study chemotaxis was expected to facilitate targeting the contaminant sources in the contamination zone, and to exhibit different behavior from nonchemotactic controls. Two key transport parameters of chemotaxis were also experimentally measured to assess the chemotactic ability in both bulk fluid and porous media.

#### **1.2** Hypothesis and Objectives

As mentioned above, chemotaxis is a bacterial property that is common to many indigenous microorganisms, and may be important in in-situ biodegradation processes of different chemical pollutants, including NAPLs and various aromatic compounds. Although many studies demonstrate that chemotaxis is quite promising to enhance the biased bacterial migration and effectiveness of bioremediation in porous media, no quantitative studies have been reported for chemotaxis in a heterogeneous porous medium with two phases (aqueous and nonaqueous phases). A two-phase heterogeneous porous system is more representative of NAPL contaminated sites, and thus will be more beneficial in understanding the role of chemotaxis in in-situ bioremediation. Therefore, in this dissertation I investigated the effect of chemotaxis on bacterial accumulation in the vicinity of residual NAPL contaminants, which are trapped in the less permeable zone of a porous microfluidic device. As one defining characteristic of contaminated sites is the groundwater flow rate, I also studied the effect of flow rate on accumulation of chemotactic bacteria in the less permeable zone.

Microfluidics facilitates this study in several different aspects. The main advantage is that it allows a predictable pore structure, so both the low and high permeable zones are well defined. This feature avoids the complications in conventional sand-packed systems, such as nonuniform packing and makes the experimental platform more controllable. In addition, its outstanding light transparency allows direct observation of bacterial movement and NAPL distribution inside the device in real time under the microscope. Moreover, the precise microscale fabrication in a microfluidic device allows one to mimic certain features that are critical for representing groundwater environment. The small size of microfluidic devices also reduces the long time needed for conventional studies on biodegradation. Therefore, based on the properties of microfluidics and the mechanism of chemotaxis, my hypothesis was:

In well-defined heterogeneous porous media, chemotaxis will facilitate bacterial migration preferentially towards NAPL attractant sources trapped in regions with

lower hydraulic conductivity, which will lead to accumulation of bacteria at chemically favorable locations. Furthermore, the groundwater flow rate will affect the impact of chemotaxis in the heterogeneous porous system.

Due to preferential migration toward chemoattractants such as toluene, chemotactic bacteria were expected to accumulate to a greater extent than nonchemotactic controls near the contaminant source in the small-scale pore network. When the convective flow rate, which was chosen in the typical velocity range of groundwater flow, was comparable to or lower than the bacterial average swimming speed, a strong chemotactic response to the chemoattractant was expected. However, if the convective flow rate was above the bacterial average swimming speed, the bacterial accumulation was expected to diminish, to the point of not producing a measurable difference from the experimental controls. Therefore, in order to test my hypothesis, I designed a series of experiments and simulation algorithms to:

- investigate the significance of chemotaxis on bacterial transverse migration towards NAPL attractant trapped in the low permeable porous zone,
- (2) explore the influence of convective flow on bacterial accumulation in vicinity of the source of organic chemicals in the heterogeneous system,
- (3) use a novel microfluidic device to evaluate the characterization parameters of chemotaxis, chemotactic sensitivity coefficient and chemotactic receptor coefficient, for all combinations of bacterial strains and chemoattractants in this study.

#### 1.3 Outline

Chapter 2 focuses on the fundamental background knowledge about the key concepts in this study, points out the pros and cons of previous relevant works, and summarizes the main research goal. Chapter 3 introduces the bacteria/attractant pairs, protocols and mathematical models, to help understand the outcomes in the following chapters. Chapters 4 and 5 are the main contents of this dissertation. Chapter 4 concentrates on the quantification of the key chemotaxis parameters by using a convection-free microfluidic device and corresponding mathematical models. Chapter 5 introduces a novel microfluidic system that successfully traps an organic contaminant in assigned positions, shows the bacterial accumulation in the vicinity of these contaminant sources due to chemotaxis, and reveals the impact of heterogeneity and flow rate on bacterial distribution. Chapter 6 concludes the dissertation, proposes unanswered questions, and recommends guidelines for future research.

#### **2** BACKGROUND

# CHAPTER 2

# BACKGROUND

#### 2.1 Introduction

The main purpose of this chapter is to introduce the key concepts in the dissertation, and briefly explain the rationale behind the selection of the materials and the experimental design.

Section 2.2 presents the mechanisms of bacterial motility and chemotaxis in bulk aqueous solution, and emphasizes the chemotaxis ability to a main group of groundwater contaminants, nonaqueous phase liquids (NAPL). Section 2.3 describes how porous media affect bacterial motility and chemotaxis and limit NAPL bioremediation in fieldscale applications, and provides a rationale for why chemotactic bacteria may enhance insitu bioremediation. Section 2.4 briefly reviews the development of microfluidic devices related to NAPL and chemotaxis study, and proposes two novel microfluidic devices: heterogeneous microfluidics (H- $\mu$ Chip) for quantification of chemotaxis to NAPL within a heterogeneous porous matrix, and convection-free gradient generator (CF- $\mu$ Chip) for measurement of key chemotaxis parameters. Section 2.6 introduces several fluorescencelabeling methods to improve the quality of image data for bacterial distributions; these methods include green fluorescent protein (GFP) transformation, live membrane staining with FM 4-64 and DAPI staining. Finally, Section 2.7 is a summary of the implications from the works in the previous sections in this chapter to my own experimental design.

#### 2.2 Bacterial Motility and Chemotaxis

#### 2.2.1 <u>Bacterial Motility</u>

In an isotropic bulk aqueous solution, the individual swimming behavior of motile bacteria can be described as a three-dimensional random walk, which is similar to Brownian motion. However, these two concepts are still different mainly in that the bacterial swimming pattern is caused by flagellar rotation, while Brownian motion is caused by molecular collision. The three-dimensional random walk consists of a series of runs and tumbles. For a peritrichous flagellar bacterium, such as *Escherichia coli*, a run happens when the flagella rotate in a coordinated counter-clockwise direction to form a flagellar bundle (Figure 2.1b), and the rotation propels the bacterium to move forward. Then, a tumble occurs when one of more of the flagella reverses the direction of rotation, as a result, the flagella bundle unravels temporarily (Figure 2.1a), after which the bacterium begins the next run in a new direction. Thus, an individual bacterial swimming pattern is composed of a series of runs and tumbles, as shown in Figure 2.1c.



**Figure 2.1** Peritrichous flagellar bacterium (a) with uncoordinated movement of the flagella, and (b) in the form of a coordinated flagellar bundle. (c) Schematic of individual bacterial movement. Motility ( $\mu_0$ ) is quantified by bacterial swimming speed ( $\nu$ ), run time ( $\tau_r$ ) and turn angle ( $\theta$ ).

Diffusion coefficients are used to quantify molecular diffusion; similarly, the bacterial random motility coefficient ( $\mu_0$ ) is used to describe the bacterial random motility. The following mathematical expression relates the random motility coefficient and the parameters of run-tumble mechanism (Lovely et al., 1997):

$$\mu_0 = \frac{v\lambda}{3} \frac{1}{1 - \langle \cos \theta \rangle}$$
 Eqn 2.1

where v is the individual bacterial swimming speed,  $\lambda$  is the run length between tumbles.  $\lambda$  is the product of v and  $\tau_r$  (run time), as shown in Figure 2.1c.  $\theta$  is the turn angle between two successive runs, and averaged for an individual bacterium from a series of changes in swimming directions, and  $\langle \rangle$  represents the average quantity.

#### 2.2.2 Bacterial Chemotaxis

For certain bacterial strains, bacterial run length ( $\lambda$ ) and tumble frequency ( $1/\tau_r$ ) can be altered by the ambient chemical concentration. When these bacteria swim up the attractant gradient, their run length increases as their tumble frequency decreases, resulting in an overall biased movement towards the locations with higher chemical concentration (Figure 2.2). This swimming behavior refers to chemotaxis. Bacterial chemotaxis is a microbial phenomenon in which bacteria respond to the concentration gradients of specific chemicals within the surrounding environment and biases the three-dimensional random walk toward favorable conditions or away from unfavorable conditions. In this dissertation, chemotaxis is referred as the biased bacterial movement toward favorable conditions rather than away from unfavorable conditions, if no additional explanation is provided.

On the molecular scale, bacterial chemotaxis in *E. coli* is regulated by a signal pathway between two groups of membrane-bound protein complexes: the methylaccepting chemotaxis proteins complexes (MCPs), which are the receptor complexes and mainly located at the pole(s) of the cell body, and the flagellar-motor complexes, which are randomly distributed over the cell membrane (Poole, 1990). Five different protein complexes on the inner cellular membrane have been identified that collect and pass along the signal from external chemical stimuli: *Trg* (taxis toward ribose and galactose) and *Tar* (taxis toward aspartate and away from certain repellents), *Tap* (taxis

toward di- and tri-peptides) and *Aer* (aerotaxis) are the minor ones (Grebe and Stock, 1998). The first four receptors are MCPs, and *Aer* is an MCP-like transmembrane protein; *Aer* is found to be a cellular redox detector, which monitors external oxygen level (Bibikov et al., 1997; Rebbapragada et al., 1997).

As shown in Figure 2.3, when the chemoattractant ligand binds to the MCPs, the receptors become methylated and deliver the signal from the attractant quickly along the chemotaxis pathway through adaptor proteins, CheW and CheA. As a result, a kind of messenger protein on this pathway, CheY, becomes dephosphorylated (CheY). Phosphorylated CheY (CheY-P) can bind to switching proteins at the flagellar motor, and make flagellar rotate clockwise, and thus cause bacterial tumbling. Therefore, an increase in the concentration of attractant decreases the amount of CheY-P, reducing the frequency of bacterial tumbling, causing the bacteria to run longer. Conversely, when bacteria swim downstream of the attractant gradient, the level of CheY phosphorylation goes up, and consequently, bacteria tumble more frequently, presumably to test new directions toward the locations with higher chemical concentration. The methylation of MCPs is a reversible reaction. As the MCPs are demethylated, the CheY becomes phosphorylated again and the tumble frequency resumes its base level. CheR and CheB, the methylesterases, are instrumental in the adjustment of this reversible process. CheR can be activated by the dephosphorylation of CheA, and then transfers methyl groups to the cytoplasmic signaling domains of the MCPs in the presense of chemoattractant; CheB impacts the process in the opposite manner. These covalent receptor modifications can activate or reset the status of receptors, and thus allow the bacteria to respond to the changes in surrounding chemical concentration. Aer chemotaxis signaling pathway

involves another mechanism without phosphorylation. Hexoses such as glucose are phosphorylated by enzyme Pts I and transported through PEP system. The dephosphorylated Pts I inhibits the activity of CheA (Macnab and Koshland, 1972).

On the cellular scale, the changes within chemotaxis pathway result in a series of changes of the run times in difference directions in presence of chemical concentration gradient. Generally speaking, the run time increases for a preferable direction, and *vice versa*. In this way, bacteria swim toward a favorable environment in the process of a chemotaxis response (Figure 2.2).

On the population scale, as depicted in Figure 2.2, bacterial chemotaxis leads to a relatively high bacterial concentration accumulation at certain high chemoattractant concentration region within its gradient, instead of even distribution for nonchemotactic bacteria or no chemical gradient environment.



**Figure 2.2** Bacterial random motility and chemotaxis. (a) In an isotropic solution, individual bacterium swims randomly. The straight lines indicate the runs, and the turn points between the lines indicate tumbles. (b) This random motion results in the even bacterial distribution on the macroscopic scale. In the bottom two figures, attractant concentration increases as the area color becomes darker. (c) Chemotaxis increases the run time toward higher attractant concentration gradient, and results in a biased motion toward the area with more attractant. (d) The chemotaxis

band forms at higher attractant concentration area from a macroscopic view. Modified from Lanning's PhD dissertation.



**Figure 2.3** The *E. coli* chemotaxis system. Ligands of stimulus molecules bind to the corresponding receptors on the cell membrane. The bindings result in a series of phosphorylation steps and alter the performance of flagellar motor system, and thus change the run length and tumble frequency on the cellular scale according to the change in the surrounding attractant or repellent concentration (Grebe and Stock, 1998).

#### 2.2.3 <u>Chemotaxis to Nonaqueous Phase Liquids (NAPL)</u>

The disposal of organic solvents used in modern industries leads to an increase in chemical pollution of groundwater, and consequentially results in an increasing threat to human health. Organic solvents in the form of the nonaqueous phase liquid (NAPL) are the most widely distributed and most threatening pollutants in groundwater system (Newell et al., 1994). NAPLs exist in nature as a separate and immiscible phase from water or air, and are simply classified into light NAPLs (LNAPLs) and dense NAPLs

(DNAPLs) based on their density comparison with water. Both LNAPLs and DNAPLs include a wide range of common contaminants. The typical LNAPL components are benzene, toluene, ethylbenzene and xylenes, which are also known as BTEX (Newell, EPA), which can be found in all cruel oil resources. 1,1,2-Trichloroethylene (TCE) and naphthalene are the most common DNAPL contaminants in the subsurface (Kavanaugh, EPA). In this dissertation, the NAPL of interest is toluene. Toluene is a very common organic solvent adopted by various industrial fields, and it becomes one of the main NAPL contaminants in the groundwater system. The NAPL contaminants are fairly toxic to life, for example, long-term exposure to toluene can cause many toxic effects on human body, including psychoorganic syndrome, visual evoked potential (VEP) abnormality, toxic polyneuropathy, cerebellar, cognitive, and pyramidal dysfunctions, optic atrophy, and brain lesions (Miyagi, 1999; Urban, 2003); TCE is reasonably listed as a human carcinogen in the Eleventh Report of Carcinogens from National Institute of Health in 2005.

Several natural microbial species are involved in degradation of many different NAPL contaminants and are reported continuously over the past decades (Farhadian, 2008). The cases include degradation to simple aromatic compounds (Harwood et al., 1984; Parales et al., 2000; Lopez-de-Victoria and Lovell, 1993), polycyclic aromatic hydrocarbons (PAHs; Grimm and Harwood, 1997; Law and Aitken, 2003), chloroaromatic compounds (Harwood et al., 1990; Hawkins and Harwood, 2002) and nitroaromatic compounds (Bhushan et al., 2000; Samanta et al., 2000). Amongst all these degrading microorganisms, many different bacterial strains are proven to exhibit the abilities of both chemotaxis and biodegradation in the presence of NAPL contaminants.

The slow dissolution of the NAPL droplets into the surrounding aqueous environment forms a concentration gradient, then the chemotactic bacteria change their threedimensional random walk correspondingly, and more bacteria are prone to migrate toward the NAPL source, which is also their carbon source, than the normal bacteria. *Pseudomonas putida* F1 is one of the five bacterial species that shows strong chemotactic response to and degrades toluene, benzene, ethylbenzene etc. (Parales et al., 2000), and is widely used to study chemotaxis. Besides, chemotaxis is proven to be essential to the formation of biofilms at the interface of different soil layers as well as between NAPL and water in the soil for several different microbial species (Pratt, 1998, O'Toole, 1998 and Prigent, 1999).

#### 2.3 Bacteria in Porous Media

#### 2.3.1 Bacterial Motility in Porous Media

Bacterial migration is restricted by the limited pore spaces within porous media. As shown in Figure 2.4, in order to accomplish the same linear displacement in bulk aqueous solution from A to B, the actual bacterial swimming trajectory may be elongated in the porous matrix. At the same time, an individual run of a bacterium is often interrupted by the interaction with surfaces of soil grains, and the turn angles are also restricted by the narrow spaces. In fact, for the wild type of *E. coli*, HCB1, its single run time between two consequent tumbles lasts approximately 1 second (Liu and Papadopoulos, 1995), and the mean swimming speed of is 22.8  $\mu$ m/s (Lewus and Ford, 2001), so the bacterial original swimming pattern can be frequently changed in the pores with comparable sizes as

bacterial run length. Berg and Turner (1990) found that the bacterial motility in 10  $\mu$ m capillary tubes was larger than that in 50  $\mu$ m ones, because the small capillary size geometrically restricted the bacterial turning angle, and also helped align the cell bodies along the axis of the tube. Chen and his coworkers (1998) also supported this experimental observation from the mathematical aspect.



**Figure 2.4** Schematic of swimming trajectories of *E. coli* in (a) bulk aqueous solution and (b) porous medium. AB represents the same linear displacement of bacterial movement.

#### 2.3.2 Bacterial Chemotaxis to NAPL in Porous Media

As stated in the Motivation section and shown in Figure 1.1, NAPL residuals are very hard to be removed from fine-grained porous media, and traditional methods of environmental remediation are too costly in terms of money, energy and time to deal with NAPL contaminations in groundwater system (Liu et al., 2005 and Boopathy, 2000). Therefore, people turn their attention to bioremediation. Bioremediation is a biological way to approach environmental contamination, and it is cheaper and easier to operate than the traditional methods, such as catalytic metal particles, excavation etc. (Langwaldt and Puhakka, 2000). The mechanism of bioremediation is to employ biological forces, such as bacteria, enzymes and plants, to consume and/or degrade the contaminants, and turn them into harmless matters. However, bioremediation is not able to function well enough in heterogeneous soil, which consists of soil layers with different permeabilities. Bacteria from bioremediation injection prefer to swimming along the groundwater flow in both high permeable (upper) and low permeable (lower) soil layers, while NAPL is usually trapped in the low permeable layer with small pore sizes. As a result, the majority of bacteria travel along with groundwater, and only a small fraction of injected bacteria functions their ability of degradation in lower soil layer, thus traditional bioremediation is not very efficient (Figure 2.5).



**Figure 2.5** (a) Schematic representation of bacterial migration in a heterogeneous aquifer (adapted from Kusy, 2005). (b) Same schematic representation in a natural heterogeneous aquifer (modified from LeBlanc et al., 1991). The blue arrows show the preferential pathway for bacteria (green) in the high permeable soil layer, and the area of yellow shaded region indicates the

chemical distribution in the low permeable layer.

Chemotaxis might improve bioremediation in the scenario mentioned above. In brief, it is because chemotactic bacteria are able to respond to the concentration gradients of specific external chemicals in its vicinity, and to migrate toward favorable conditions or away from unfavorable conditions. The low permeable soil layer has a higher concentration of NAPL component, which is favored by chemotactic bacteria like *Pseudomonas putida* F1, so the bacterial population is expected to increase in the contaminant layer (Figure 2.5), and thus chemotactic bacteria should be able to improve the efficiency of bioremediation.

Bacterial chemotaxis in bulk aqueous solution was well characterized in different laboratory-scale studies with or without flow (Adler, 1966; Mesibov et al., 1973; Marx and Aitken, 2000; Parales et al., 2000; McClaine and Ford, 2002; Law and Aitken, 2005; Lanning et al., 2004, 2008). Capillary assays (Mesibov et al., 1973), stopped-flow diffusion chamber assays (Ford et al., 1991), agarose plug assays (Parales et al., 2000) and T-sensor assays (Lanning et al., 2008) could be representative in the series of studies on bacterial chemotaxis in bulk aqueous media. All these studies successfully quantified chemotactic accumulation in very short time. However, this microbial phenomenon in porous media, which is truly critical to the understanding and application of bacterial chemotaxis in contaminated groundwater system, was only recently focused on. Some experiments were conducted to observe chemotaxis to organic chemicals specifically in a flow-free and porous environment. Bacterial chemotaxis to NAPL compound naphthalene was quantified in a modified capillary filled with glass beads (Pedit et al., 2002). Olson et al. (2004) reported a strong chemotactic response of *Pseudomonas putida*  F1 to trichloroethylene (TCE) in a glass bead column by magnetic resonance imaging. On the other hand, it was demonstrated that convective flow influenced the effect of chemotaxis on the transverse direction in homogenous and heterogeneous porous media on multiple scales, which included microfluidic porous T-sensor (Long and Ford, 2009), packed column (Wang et al., 2008 and 2009) and two-dimensional flow-through microcosms (Bauer et al., 2008; Strobel et al., 2011). All these experimental approaches drew similar conclusions that bacterial chemotaxis was still significant under slow convective flows. However, all these conclusions were based on the results from aqueous-phase attractants, whereas natural systems typically have nonaqueous phase liquid (NAPL) contaminants. Conventional scales like packed column and microcosm were too hard to include a second liquid phase chemical in the experimental process due to various reasons, such as nonuniform packing, no direct visualization etc. Microscale techniques like microfluidics allows delicate manipulation on small amount of liquid, and can be used to study NAPL problems in an aqueous surrounding. In the next section, I will introduce the microfluidic designs used for study of bacterial chemotaxis, especially for study of chemotaxis phenonmenon in presence of NAPL.

#### 2.4 Application of Microfluidics in This Study and Related Research

Microfluidic devices have proven to be effective tools in a wide range of scientific fields, (Whitesides, 2006), and have some ideal features for the study of bacterial chemotaxis. Microfluidic devices allow accurate fabrication of microscopic scale structures and precise manipulation of very small amounts of fluid, which is ideal for the study of NAPL contaminants in pore-scale geometries that are representative of the natural aquifer environment. Moreover, the microscale channel operates under laminar

flow in most scenarios, so that the concentration gradient of attractant is smooth and mathematically predictable. Its absolute transparency and small size allow direct and quantitative measurement of the bacterial distributions inside the device under a microscope.

#### 2.4.1 <u>Heterogeneous Microfluidic Device (H-µChip)</u>

Amongst the earlier studies, microfluidic devices with pore-scale structure were created to study colloid transport (Wan and Wilson, 1994a and 1994b; Auset et al., 2004). Gradually, a variety of microfluidics designs were applied to the study of bacterial chemotaxis with convective flow. Under flow conditions, parallel-flow devices were among the first approaches to generate steep and steady concentration gradients and assess chemotaxis by the extent of transverse bacterial movement towards the chemoeffector stream (Mao et al., 2003; Lanning et al., 2008; Englert et al., 2009). Long and Ford (2009) observed bacterial chemotaxis in a direction transverse to flow under fluid velocities typical of groundwater flow rates in a T-shaped homogeneous porous channel with a staggered array of cylindrical posts. Singh and Olson (2012) created a heterogeneous porous microfluidic device to study transverse chemotaxis, and an increase of chemotactic bacterial population was detected in the low permeable regions containing attractant. All the previous studies successfully detect the effect of bacterial chemotaxis in porous structure under groundwater flow rates; however, they also all treated the contaminants as aqueous phase chemicals other than organic phase ones. A two-phase heterogeneous porous system is more representative of the actual NAPL contaminated sites. Wan and coworkers published several studies of bacterial transport in two-phase systems with water and air in the microfluidic device (Wan, 1994a and Wan,
1994b), and many researchers continued with this topic to study unsaturated (liquid/gas interfaced) porous media at different scales (Crist, 2004, Garguilo, 2008, Powelson, 2001, Sirivithayapakorn, 2003, Chen, 2009). Wang and coworkers (2012) successfully developed a single-pore microfluidic device to quantify the chemotaxis effect in the vicinity of a stable NAPL/water interface. Although this design mimicked the different pore scales for contaminant source and bacterial pathway, it was still not a porous medium. A more complex experimental platform of microfluidics (Figure 2.6) was developed originally by Lanning (2004) in order to mimic the heterogeneous NAPL contamination condition illustrated in Figure 1.1 to a greater extent. The advantage of this microfluidic device over the "single-pore" one is that it captures some of the essential features of the contaminated soil: soil heterogeneity and NAPL entrapment. It achieves a microscopic level pore structure, which consists of a high permeable channel adjacent to a low permeable porous network with NAPL ganglia. In addition, the NAPL sources in the low permeable region are trapped in a predictable manner for quantitative analysis and evaluation using mathematical models. The heterogeneous microfluidic device (H- $\mu$ Chip) used in this study was modified from this version with a finer porous network, and was used to study bacterial chemotaxis in response to the attractant sources.



**Figure 2.6** Design of the original porous microfluidic device. (a) The overall diagram illustrates the wide horizontal channel as the macropore with high permeability and the network of micropores as the region with low permeability. (b) A more detailed diagram of the low permeable region shows the dimensions of the channels and ganglia. The depth of the straight pores is approximately 100  $\mu$ m, and that of the ganglia is approximately 200  $\mu$ m. (c) The detailed diagram shows the patterns etched away from the top and bottom glass pieces in the low permeable region. (d) The toluene droplets have been dyed red and are trapped within the circular ganglia of the micromodel network (adapted from Lanning, 2004).

## 2.4.2 <u>Convection-Free Gradient Generator (CF-µChip)</u>

The quantification of chemotaxis is always a challenge. Chemotaxis was proved to be useful to bioremediation by different literatures qualitatively, but not many studies were done to analyze chemotaxis quantitatively. Its quantification is characterized by two parameters, chemotactic sensitivity coefficient  $\chi_0$  [m<sup>2</sup>/s] and chemotactic receptor constant  $K_c$  [mol/L]. The chemotactic sensitivity coefficient represents the redirected bacterial movement resulted from the chemotactic response to a certain kind of chemical, and the chemotactic receptor constant represents the bacterial propensity to bind the chemoattractant with the chemotactic receptors (Ford and Harvey, 2007). Mathematical models on diffusion and advection were applied to evaluate the values of the parameters. In order to provide precise measurement, the models need to be simplified as much as possible, so that chemotaxis can be the main or even the only variable that affects the final results. Therefore, an advection-free system with linear attractant concentration gradient at steady state is preferred for both experimental observation and computational fitting.

Multiple approaches were developed to produce time-invariant concentration profiles of attractant without convective flow, and they all basically shared the same operational principle, which was to utilize a hydrogel layer or porous membrane to connect the channels of attractant and bacteria (Diao et al., 2006; Wu et al., 2006; Cheng et al., 2007; Kalinin et al., 2009; Ahmed and Stocker, 2010). The hydrogel and the porous membrane obstructed advection from the testing channel, and helped to establish a steady concentration gradient of the chemical due to pure diffusion. Since there was no interference of convective flow, these studies of bacterial chemotaxis in response to a steady concentration gradient under a flow-free condition could be used to evaluate the bacterial motility and chemotaxis parameters, which are the chemotactic sensitivity coefficient and chemotactic receptor constant. However, all of these attempts were still not precise to create a predictable linear gradient, because the interface between the aqueous phase and the hydrogel/membrane, and the properties of hydrogel/membrane itself were subject to unpredictable changes. These changes added some unnecessary complexity into the chemical diffusion and bacterial interaction with material surface, and made it difficult to obtain accurate values of chemotaxis parameters from mathematical modeling. A microfluidic palette design (Atencia et al., 2009) achieved multiple flow-free concentration profiles of attractants in one aqueous phase in a microscale circular chamber by the precise pressure balances among the chamber inlets, which could be used to study the bacterial sensitivity surrounded by different attractant sources, or bacterial response to a transient environmental change, etc. Atencia et al. (2012) developed the prototype of the first convection-free gradient generator (CF- $\mu$ Chip), which uses the mechanism of pressure balance from the microfluidic palette design and the knowledge from the previous methods, to create a well-defined gradient without flow in a straight channel that is amenable to mathematical description.

Another critical factor that the previous studies did not take account into was the coupling effect of chemotactic sensitivity coefficient and chemotactic receptor constant. Different combinations of the values of these two parameters could generate similar chemotactic effect, so an imprecise measurement of one parameter would lead to an incorrect value of the other. Measurement for these two parameters has been quite a challenge, especially for the chemotactic receptor constant. This study used a modified design from Atencia's CF- $\mu$ Chip and successfully eliminated the coupling effect by changing the attractant concentration.

## 2.5 Bacterial Fluorescent Labeling and Imaging

An alternative data collecting and analytical method was developed to replace the conventional and time consuming counting method on bacterial density. Generally speaking, bacterial density was expressed as certain signal intensity, like light intensity, instead of bacterial counting number. Several previous studies adopted similar methodology and successfully recorded bacterial distribution according to chemotaxis. Ford and coworkers (1991) constructed stopped-flow diffusion chamber assays (SFDC) and read the chemotactic bacterial density as their light intensity from phase contrast under bright field; same method was used in the single-pore microfluidic assay by Wang and coworkers (2012). However, light intensity reading had big background noise from device materials, dust etc. Sherwood and coworkers (2003) used immunomaganetic tracers to label bacteria and magnetic resonance imaging (MRI) to detect the bacterial distribution in a glass-beads packed column; this method reduced background noise to a great extent, but the bacterial movement in the column could not be directly seen. Fluorescence labeling could reduce background noise and allow visualization of bacterial population distribution instantaneously under the microscopes.

The transformation of green fluorescent protein into *E. coli* bacterial strains is a well-understood case. A common method is to use the arabinose operon (Hanahan, 1983). As shown in Figure 2.7, the single gene for GFP is embedded into the DNA code of the plasmid for arabinose operon. Arabinose molecule interacts with the regulatory protein *araC*, which sits on the  $P_{BAD}$  promoter, and consequently changes the protein's conformation. This change facilitates transcription of the gene by RNA polymerase, and thus GFP is transcribed. Ultra violet (UV) light exposure excites GFP molecule, and

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cause the protein to glow in green fluorescence. GFP transformation allows live observation.



Figure 2.7 Schematic of green fluorescence protein expression through arabinose catabolism.

Other live cell fluorescence stains are also available. Membrane dye N-(3-Triethylammoniumpropyl)-4-(6-(4-(Diethylamino) Phenyl) Hexatrienyl) Pyridinium Dibromide (abbreviated FM 4-64) is a good example. FM 4-64 is nontoxic to cells and is believed to bind the outer leaflet of the plasma membrane where this dye becomes intensely fluorescent (Haugland, 1996). This method of labeling has been widely used to selectively visualize plasma membrane of a variety of individual cells including bacteria (Vida and Emr, 1995), and allows live observation of cellular activities. Because chemoreceptors are transmembrane proteins embedded in the inner membrane (Stock and Mowbray, 1995), we do not expect any interference between the FM 4-64 membrane staining and the chemotaxis cascade pathway.

# 2.6 Summary of the Experimental Design

In this study, *P. putida* F1 and its nonchemotactic mutant *P. putida* F1 CheA were used as the study model. *E. coli* HCB1 and HCB437 (smooth-swimming mutant) were also tested for comparison. Microfluidics was chosen as the method to study bacterial chemotaxis due to its advantages as mentioned in Section 2.4. Two different microfluidic designs were used: the heterogeneous microfluidic device (H- $\mu$ Chip) and the convectionfree gradient generator (CF- $\mu$ Chip), as shown in the next chapter Materials and Methods. H- $\mu$ Chip was used to study bacterial chemotaxis in a heterogeneous porous matrix design with residual NAPL ganglia, and CF- $\mu$ Chip was used to measure relatively accurate values of key chemotaxis parameters.

For the H-µChip study, one bacteria/attractant pair was tested. Two flow rates, 0.25 and 5 m/d, were chosen to study the influence of flow rate on the chemotaxis effect. They are within the range of typical groundwater flow rates from 0.15 to 15 m/d (Harter, 2003). The three groups of variables in the H-µChip experimental design are summarized in Table 2.1. Representative publications relative to this study are summarized in Table 2.2;  $\sqrt{}$  means that specific work contains this feature in its study, and H-µChip experiment is also compared with these works in this table.

Bacterial strain	NAPL component	Flow rate (m/d)
		0
P. putida F1	T. I	0.25
P. putida F1 CheA <sup>a</sup>	loluene	0.5
		5.0

Table 2.1 The test variables in the H- $\mu$ Chip experiments

<sup>a</sup> This is the nonchemotactic bacterial control.

	Chemotaxis	NAPL	Two phase	Porous Medium	Heterogeneity	Convective flow	Quantitative Analysis
Wan et al. 1994			$\checkmark$	$\checkmark$		$\checkmark$	$\checkmark$
Pedit et al. 2002	$\checkmark$	$\checkmark$		$\checkmark$			$\checkmark$
Olson et al. 2004	$\checkmark$	$\checkmark$		$\checkmark$			$\checkmark$
Long and Ford 2009	$\checkmark$			$\checkmark$		$\checkmark$	$\checkmark$
Wang and Ford 2009	$\checkmark$			$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$
Strobel et al. 2011	$\checkmark$			$\checkmark$		$\checkmark$	$\checkmark$
H-μChip		$\checkmark$	$\checkmark$		$\checkmark$		

Table 2.2 Comparisons among the H-µChip study and previous representative works

For the CF-µChip study, the bacterial strains were divided into two groups (see Table 2.3). One was *P. putida* F1 and its nonchemotactic mutant *P. putida* F1 CheA. The

attractant for the first bacterial group was toluene dissolved 10% random motility buffer (RMB), and the two test concentrations were 0.2 and 2 mM. The other group was *E. coli* HCB1 and *E. coli* HCB437. HCB437 is a smooth swimming mutant and served as a nonchemotactic control; the attractant was  $\alpha$ -methylaspartate, and the two test concentrations were 0.3 and 3 mM in 10% RMB. The three groups of variables in the CF- $\mu$ Chip experimental design are summarized in Table 2.3.

Bacterial strain	Attractant	Attractant Concentration (mM)
<i>P. putida</i> F1 <i>P. putida</i> F1 CheA <sup>a</sup>	Toluene in 10% RMB	0.2 2.0
<i>E. coli</i> HCB1 <i>E. coli</i> HCB437 <sup>a</sup>	α-methylaspartate in 10% RMB	0.3 3.0

Table 2.3 The test variables in the CF-µChip experiments

<sup>a</sup> This is the nonchemotactic bacterial control.

# CHAPTER 3

# **MATERIALS AND METHODS**

# **3.1** Introduction

This chapter describes the protocols used in this study, including preparation of bacteria/attractant system, staining, microfluidic fabrication, and image analysis. It details the methods used to correlate bacterial density, optical density (OD), and fluorescence intensity. It also provides the rationale about selection of mathematical modeling equations, which are used to support experimental observations on bacterial chemotaxis, and to quantify the results with accurate parameters.

#### **3.2** Preparation of Bacterial Strains and Attractants

Two bacterial and attractant systems were used in this study. One bacteria/attractant pair was *P. putida* and toluene. *P. putida* F1, the wild type, was obtained from C. S. Harwood (Parales et al., 2000) and nonchemotactic mutant P. putida F1 CheA from R. E. Parales (Liu et al., 2009). An aliquot (300 µL for P. putida) of frozen stock at -80 °C was used to inoculate 100 mL of growth media in a sealed 200 mL glass bottle. The Modified Hutner's Mineral Base for *P. putida* contained basic components of Hutner's Mineral Base (Olson, 2004), 600 µg LB powder (Miller, ACROS LB Broth), with 30 µL toluene (Sigma-Aldrich, HPLC grade) injected into the gas phase. Oxygen (GT&S, oxygen compressed USP) was injected at 5 psi for 10 minutes to ensure a sufficient supply. Bacteria were cultured on the Thermo Scientific Incubated and Refrigerated Shaker (Model MaxQ 4000) with a rotation rate of 150 rpm at 28 °C. When the optical density (measured at 590 nm in Beckman Coulter, DU 730) reached 0.80 (corresponding to the mid-exponential phase of growth), bacteria were harvested and filtered from the culture media with a 0.22 µm membrane filter (Millipore, GSWP14250), and resuspended in 10% Random Motility Buffer (RMB, 11.2 g K<sub>2</sub>HPO<sub>4</sub>, 4.8 g KH<sub>2</sub>PO<sub>4</sub>, and 0.029 g EDTA per liter of deionized water) to a density similar to the one when harvested.

*P. putida* F1 was dyed with the vital membrane stain FM 4-64 (Invitrogen) at a concentration of 5  $\mu$ g/mL for 10 minutes and F1 CheA was dyed with 100 mg/L DAPI (Invitrogen) for 30 minutes, and both bacterial suspensions were washed twice before the final use. The movement of stained bacteria was observed under Wide-Field Microscope (Olympus IX-70) and compared visually with the unstained bacteria. There was no

observable change in motility between the unstained and FM 4-64 stained bacteria, as the run length and tumbling frequency appeared to be the same between the two groups, and both unstained and stained bacteria swam actively by visual comparison. Quantitative analysis was done and also showed that the dye FM 4-64 itself did not affect the bacterial motility (Appendix E). The two bacterial suspensions with different dyes were then mixed for later experimental use. The bacteria suspension was also mixed with 1.2 mM sodium nitrate (Sigma-Aldrich, ACS reagent), an electron acceptor to maintain bacterial motility (Bauer et al., 2008). Toluene (Sigma-Aldrich, HPLC grade) aqueous solution was also prepared for the measurement of chemotaxis parameters, and the toluene concentrations were 0.2 and 2 mM in 10% RMB.

The other bacteria/attractant pair was *E*. coli and  $\alpha$ -methylaspartate. *E. coli* HCB1 was selected because it presented a strong chemotactic response to  $\alpha$ -methylaspartate (Lanning et al., 2008), which is a non-metabolizable analog of aspartate. The preparation of the frozen aliquots for *E. coli* HCB1 (wild type) and HCB437 (smooth swimming mutant), which were generously provided by Dr. Howard Berg at Harvard University (Wolfe et al., 1987), was the same as that for the *P. putida* strains. HCB437 mutant could not perform the tumble function, so the bacteria were unable to adjust their swimming direction in a changing chemical environment, and therefore, could not exhibit chemotaxis. *E. coli* HCB1 was genetically tagged with green fluorescent protein (Bio-Rad, pGLO bacterial transformation kit), and HCB437 was treated with the same DAPI staining protocol as *P. putida* F1 CheA. A 100 µL volume of *E. coli* strains were cultured aerobically in 50 mL TB media [0.50 g tryptone (BD BactoTM) and 0.25 g NaCl (Fisher Scientific Certified A.C.S.)]. 100 µL of 10 mg/mL ampicillin (Acros, 99%) and 1 mL of

100 mg/mL L-(+)-arabinose (Acros, 99+%) were added into HCB1's medium to provide selective pressure for plasmid-containing and fluorescing bacteria. The  $\alpha$ -methylaspartate (Sigma-Aldrich) concentrations were 0.3 and 3 mM in 10% RMB. The harvesting, mixing protocols for *E. coli* were the same as those for *P. putida*.

# **3.3 Design and Fabrication of the H-µChip**

The design used for the heterogeneous microfluidic device (H- $\mu$ Chip) is presented in Figure 3.1a, in which the higher permeable region is represented by the horizontal channel above and the lower permeable region/the contaminant layer is represented by the fine cross-hatched pore network below with aligned circular ganglia. Figure 3.1b shows a closer view of the fine pore network with one circular ganglion. The dimensions of the channels and network are typical of pores and soil grains within a low permeable layer. The ganglia and the channel/network patterns were etched, by hydrofluoric acid, in two separate borofloat glasses sheets, as shown in Figure 3.1c.



**Figure 3.1** (a) Full view of the heterogeneous microfluidic device (H- $\mu$ Chip); the two rounded ends of the horizontal channel are bacterial inlets/outlets, and the third one at the bottom of the device is the NAPL inlet. (b) Zoomed-in view of a part of the fine-grained pore network. Each of the straight channels has a width of 20  $\mu$ m. (c) 3D expanded view of the fine-grained network shown in (b).

The microfabrication process followed the photolithography procedure from Roper et al. (2003). First, the photomask was designed. CorelDraw X4 was used to depict the black/white microfluidic design (Figure 3.1a) on an  $8.5'' \times 11''$  page. The patterns for one layer were confined to a  $5'' \times 5''$  square because these are the dimensions of the glass sheet that are available for microfluidic fabrication. White and black colors were chosen for the appropriate features; the black parts on the design represented the areas that were etched away in the glass-etching step. Then the design was transferred onto a mask of transparent film. Figure 3.1 shows the microfluidic design. Dimensions of the main features are as follows: the channel depth was chosen to be 20  $\mu$ m, so that the narrow space between channel ceiling and floor did not interfere with bacterial motility (DiLuzio et al., 2005), and ganglia have a depth of 100  $\mu$ m to retain the toluene droplets. Each of the straight channels in the porous network has a width of 20  $\mu$ m, which was representative of the actual pore size within a contaminant layer in sandy soil (Hassink, 1993).

The glass etching procedure, illustrated in Figure 3.2, was conducted in the Class 100 clean room in the laboratory of Dr. James Landers in the Department of Chemistry at the University of Virginia. The purpose of glass etching was to create channel patterns of the H- $\mu$ Chip according to the design. The 5" × 5" mask was cut from the transparent film and placed on a 1.1 mm thick Borofloat photomask glass blank (size: 5" × 5", Telic Co.) with a 530 nm layer of AZ1518 positive photoresist on a 120nm chrome layer, exposed to collimated UV light (Optical Associates Inc.) at 26 mW/cm<sup>2</sup> for 5 s. After exposure, the glass blank was coated with photoresist developer (AZ@400K 1:4 diluted, Clariant Corp.) for 1min and rinsed by deionized water. Then it was placed in chromium photomask etchant (CR-7S, Microchrome Technologies Inc.) until chromium was fully removed from the exposed patterns, after which it was rinsed thoroughly using with deionized water. The glass was then placed in etching solution of 200 mL HF and 30 mL HNO<sub>3</sub> with an etching rate of 7  $\mu$ m/min for 14 min. A 100  $\mu$ m high channel was expected

to form under these conditions. After etching, the glass was rinsed with excessive amounts of deionized water (2 L of volume for a  $5'' \times 5''$  mask) and dried with compressed air. The dimensions of the features on the glass were measured by a highresolution profilometer (XP-1, Ambios Technology). AZ photoresist left on the glass was removed by stripper AZ 300T (Clariant Corp), and chromium was removed by chromium photomask etchant. The etched surface was cleaned by Piranha solution (H<sub>2</sub>SO<sub>4</sub>:H<sub>2</sub>O<sub>2</sub> 3:1 v:v) for 30 min.



**Figure 3.2** The basic steps in the procedure of glass etching. The various layers include (a) the mask, (b) the positive photoresist layer, (c) the chromium layer, and (d) the Borofloat glass. The etching process consists of six steps: (I) UV light exposure, (II) development, (III) chromium removal, (IV) acid etch, (V) photoresist removal by stripper, and (VI) final chromium removal.

As mentioned above, the microfluidic system was comprised of two separate glass layers: the top layer with the macrochannel and pore network and the bottom layer with the ganglia. The top layer was drilled with access holes at the three ends of channels (Figure 3.1a) using a 1.1-mm-diameter diamond-tipped drill bit (Crystalite Corp., Lewis Center, OH). The two etched glass layers were irreversibly sealed together by thermal bonding at 690 °C.

The connections to access holes were made of polydimethylsiloxane (PDMS), a kind of elastic polymer after curing. 35 g PDMS was prepared with a 10:1 (v:v) mixture of its base and curing liquid agent (184 Silicone elastomer, SYLGARD), and subject to vacuum for 45 min to minimize gas bubbles. The mixture was then poured into an 8 cm (W) × 10 cm (L) × 5 cm (H) plastic box, and put into a 70 °C oven overnight until PDMS cured to form a solid state. 1 cm × 1 cm × 1 cm PDMS blocks were cut out and a hole for the connector was made using a stainless needle of GA 21. Then the PDMS blocks were bound at the locations of access holes by plasma binding for 1 min at high radiation level. A complete H-µChip with the PDMS block connections is shown in Figure 3.3. Needles of GA21 (IV1 PrecisionGuide Needle, BD) were clipped to form 1 cm long pins, which were used to connect Teflon tubing (Tub 1/16 × .030 × 5 ft, Upchurch Scientific) to the holes in the chip.



**Figure 3.3** A complete H-µChip with the PDMS blocks at the inlets and outlets. The size of the device is comparable to a US quarter. The red color of the PDMS blocks is resulted from the hydrophobic dye Red Oil O in the toluene after the toluene solution contacts the PDMS polymer.

# **3.4 Design and Fabrication of the CF-µChip**

The mechanism of how convection-free gradient generator (CF- $\mu$ Chip) worked was well introduced by Atencia and coworkers (2012), as shown in Figure 3.4. Generally speaking, Atencia proposed an equal pressure method to obtain a diffusion-only environment in a microfluidic channel (Figure 3.4). This convection-free gradient generator is composed with multilayers. The top layer (Figure 3.4a) allows aqueous solutions to be injected into its horizontal main channel and flow along side each other. The same locations in x direction are subject to the same pressure. Vias with the identical pressure connect the top layer to the buried channel in the bottom layer (Figure 3.4b), so that the pressures at both ends of the cross channel are equal, and thus achieve the convection-free condition (Figure 3.4c). The cross channel is 40  $\mu$ m high, 600  $\mu$ m wide and 1.5 mm long. Because the vias are adjacent to the sidewalls of the horizontal channel, the concentration of matter in a via is not affected by flow oscillation and transverse dispersion between the two different flows, and remains unchanged from the injection (Figure 3.4d). Replicate cross channels in the bottom layer can ensure multiple measurements under identical conditions in the same device (Figure 3.4e).



**Figure 3.4** Diagram of convection-free gradient generator (Courtesy of Dr. Javier Atencia). (A) Vias at the same cross section of the horizontal channel (top channel) connect to (B) the two ends of a buried channel in the bottom layer. (C) Two aqueous fluids with different chemical compositions flow parallel to each other in the horizontal channel at same velocity, generating identical pressure at the two symmetric vias, resulting in a diffusion-only linear concentration profile in the buried channel. (D) The vias are away from the diffusive interface between the two fluid streams, and thus the concentration gradient in the buried channel is not affected by the flow oscillation and diffusive region in the horizontal channel. (E) At a desired flow rate, four independent buried channels (a, b, c, d) can achieve the same full concentration gradient of the chemical, and provide replicate conditions for bacteria in the same device. Adapted from Atencia

A new device was developed using PDMS channels based on the same mechanism. The reason why PDMS is used instead of the original material glass is because PDMS has excellent air permeability and can provide sufficient oxygen for bacteria to keep their motility. The new CF-µChip is still composed with three layers.

The centerpiece was made from two pieces of thin cover glasses ( $24 \times 50$  Fisher Scientific No. 1.5, 175um thickness) sandwiching a mixture of black ink (Sharpie, Sanford) and super glue (loctite). The black ink was used to stop the background noise. The glue mixture should be put onto the top of one of the cover glasses quickly and evenly. The new assembled centerpiece was perforated with a sand blaster (Airbrasive 6500, s.s. white) to make holes. To facilitate registration and hole-sand-blasting we used a tape stencil with holes designed with Adobe illustrator and cut out with a laser cutter (VersaLASER, Universal Laser Systems Inc., AZ). The material of the other two layers was replaced by PDMS. The glass molds for the PDMS layers were prepared according to the same photolithography protocol for H-µChip. PDMS was cured on top of the mold patterns, and then peeled off for assembling. A convenience of using PDMS to assemble the device is that the bottom layer with the cross channels can be reversibly bonded with the centerpiece by PDMS's natural stickiness, and it can be cleaned and reused easily just by peeling it off from the centerpiece. The top layer was still plasma bonded with the centerpiece. The bacterial suspension and attractant solution were injected into the channel by syringe pump (PHD 2000 Infusion, Harvard Apparatus) and pushed at a constant speed of 1.0 mL/h, which was comparable to 0.38 mm/s in the main channel and Reynolds number Re = 0.28, which means that the two streams are creeping flows and only diffusion happens on their transverse direction.

#### **3.5** The Correlation Between Bacterial Density and Fluorescence Intensity

One conventional way to determine bacterial density is to count individual cells, which is time-consuming and error-prone. Instead, for this analysis, it was assumed that the fluorescence intensity of each cell was similar to each other in the population, thus allowing the light intensity to be correlated with the bacterial concentration in terms of optical density.

GFP tagged *E. coli* HCB1 was cultured and harvested when its optical density (OD) value at 590 nm reached to 0.80. The collected bacteria were filtered and resuspended in 10% RMB, to form a concentration set of eight from OD<sub>590</sub> 0.1 to 0.5, which covered the working OD<sub>590</sub> value of 0.4. Part of the solutions was stained with acridine orange (AO) protocol, and bacterial density was calculated from the counting number of the AO stained cells. With 10% RMB as control, images of GFP fluorescence from the eight bacterial suspensions were captured by the Wide-Field microscope (Olympus IX-70) in Keck Center of Cellular Imaging at the University of Virginia. Image J was used to record the fluorescence intensities from the images. Then calibration curves were drawn to relate OD<sub>590</sub> values with bacterial densities from AO counting and also fluorescence intensities.

#### 3.6 Image and Data Analysis

The Wide-Field epifluorescence microscope (Olympus IX-70) was used for all experimental observations and imaging recording with the  $2\times/0.05$  (Olympus, Plan) and  $20\times/0.40$  objective (Olympus, PlanFI). An arc lamp and dichroic filter (Chroma 51001bs, double coated for TRITC and DAPI) were used to look at both the FM 4-64 (excitation at 515 nm, emission at 640 nm) and DAPI (excitation at 345 nm, emission at 455 nm) stained *P. putida* strains, and FITC and DAPI filters (Chroma31013 602 NB) were used for GFP (excitation at 385 nm, emission at 508 nm) tagged and DAPI stained *E. coli* strains. Images were then converted to 8-bit during the import to Image J. The Grouped Stack Projector was used to take the average image from the repeated images at same location, in order to smoothen the curve of bacterial distribution. The data were then normalized for further comparisons.

# 3.7 Mathematical Modeling, Computational Fitting and Statistical Analysis

The first question to ask before choosing the necessary mathematical models is how many spatial coordinates are required to adequately specify the experimental system; to put into other words, should the models be in forms of 1D, 2D or 3D equations? This question can be answered by evaluating the variation of the fluid velocity in the microfluidic device in each dimension and considering its effect on bacterial distribution. In some cases, a gradient in the velocity near the channel wall can lead to the so-called "butterfly effect" (Lanning, 2004).

Weigl (1996) first discussed the effect of a parabolic velocity profile on the shape of the diffusive front of an analyte in microfluidic devices, where the extent of transverse

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diffusion across the channel was related to the channel depth. As the shape of the interdiffusion zone between two streams was similar to a butterfly at a cross-section of a microfluidic channel, this phenomenon was termed the "butterfly effect".

The extent of the "butterfly effect" is quantified by the dimensionless expression in Equation 3.1 (Kamholz, 1999),

$$\frac{d}{y} = \frac{d}{\sqrt{6D_N t}} = \frac{d}{\sqrt{6D_N (z/u_{z,avg})}}$$
Eqn 3.1

where *d* stands for the depth of the channel, and *y* is the mean diffusion distance using Einstein's equation for diffusion ( $\langle y \rangle^2 = 6D_N t$ ),  $D_N$  is the diffusion coefficient of the analyte, and the elapsed time of the experiment *t* equals the total distance traveled down the length of the channel *z* divided by the average fluid velocity ( $u_{z,avg}$ ).

If the value of the dimensionless expression in Equation 3.1 is significantly smaller than 1, the "butterfly effect" can be neglected. As indicated by the equation, a smaller *d* could reduce the "butterfly effect". However, if *d* were so shallow as to be comparable to the bacterial run length, the bacterial motility would be altered. If the distance between the "ceiling" and the "floor" of the channel was smaller than 10µm, the bacterial movement could be biased (DiLuzio, 2005). Thus, the height was chosen to be 20µm in order to diminish the impact on bacterial swimming behavior and keep the height sufficiently small to justify a 2D description. The parameter values for  $D_N$ , which for bacteria is the random motility coefficient ( $\mu_0$ ) and attractant is the diffusivity ( $D_a$ ), are reported in Table 6.1, the travel length *z* is 3 mm for the horizontal channel, 30 µm for the fine channels, and  $u_{z,avg}$  ranged from 0.25 to 5.0 m/d. Thus, the values of the dimensionless expression ranged from 0.01 to 0.08, and it was assumed that "butterfly effect" had a negligible impact on transverse diffusion in the direction of the channel depth. Therefore, a 2D mathematical model was sufficient to simulate the bacterial chemotaxis in the microfluidic device and evaluate the chemotactic properties.

A two-dimensional form of the advection-dispersion governing equation was suitable to describe bacterial transport with the effect of chemotaxis in H- $\mu$ Chip. A twodimensional Brinkman equation is adopted to solve the flow profile in the porous microfluidic device,

$$\frac{\rho}{\varepsilon_p} \frac{\partial \mathbf{u}}{\partial t} + \nabla \cdot \left[ -\frac{\mu}{\varepsilon_p} (\nabla \mathbf{u} + (\nabla \mathbf{u})^T) + p\mathbf{I} \right] = -\frac{\mu}{\kappa_{br}} \mathbf{u}$$
Eqn 3.2  

$$\nabla \cdot \mathbf{u} = 0$$

and **u** denotes the flow velocity vector (m/s),  $\rho$  the fluid density (kg/m<sup>3</sup>),  $\varepsilon_p$  the porosity (dimensionless),  $\kappa_{br}$  the permeability of the porous medium (m<sup>2</sup>),  $\mu$  the dynamic viscosity (Pa.s), and *p* the pressure (Pa). The advection-dispersion governing equations that follow are modified from Olson et al. (2008),

$$\frac{\partial a}{\partial t} = D_{e,a} \frac{\partial^2 a}{\partial x^2} + D_{e,a} \frac{\partial^2 a}{\partial y^2} - \frac{\partial (v_x a)}{\partial x} - \frac{\partial (v_y a)}{\partial y}$$
Eqn 3.3

$$\frac{\partial b}{\partial t} = D_{e,b} \frac{\partial^2 b}{\partial x^2} + D_{e,b} \frac{\partial^2 b}{\partial y^2} - \frac{\partial (v_x b)}{\partial x} - \frac{\partial (v_y b)}{\partial y} - \frac{\partial (v_{Chx} b)}{\partial x} - \frac{\partial (v_{Chy} b)}{\partial y}$$
Eqn 3.4

where

$$D_{e,a} = \varepsilon_p D_a$$
  

$$D_{e,b} = \varepsilon_p D_b$$
  
Eqn 3.5

$$v_{Chx} = \frac{2}{3} v_b \tanh(\frac{\chi_0}{2v_b} \frac{K_c}{(K_c + a)^2} \frac{\partial a}{\partial x})$$
  
Eqn 3.6  
$$v_{Chy} = \frac{2}{3} v_b \tanh(\frac{\chi_0}{2v_b} \frac{K_c}{(K_c + a)^2} \frac{\partial a}{\partial y})$$

and *a* refers to the attractant concentration, *b* the bacterial concentration,  $v_x$  and  $v_y$  the longitudinal and transverse fluid velocity solved from the two-dimensional Brinkman equation,  $D_a$  the diffusion coefficient for attractant,  $D_b$  the bacterial random motility, and  $D_{e,a}$ ,  $D_{e,b}$  are their effective values.  $v_{Chx}$  and  $v_{Chy}$  are the longitudinal and transverse chemotactic velocities describing the convective transport of bacteria caused by chemotaxis in attractant gradients,  $\chi_0$  the chemotactic sensitivity coefficient and  $K_c$  the chemotactic receptor constant. The time derivative on the left hand side of Equation 3.3 goes to zero, when the system reaches steady state for the attractant.

The commercial finite-element solver COMSOL Multiphysics 4.3 was used to solve the system of differential equations for the attractant and bacterial concentrations. The setup of conditions and selection of modules are included in the modeling sections in Chapter 4 and 5, and also in appendix. The method of least squares is used to approximate the fitting solution. The best fit in the least-squares sense minimizes the sum of squared residuals, a residual being the difference between an observed value and the fitted value provided by a model. Two-way ANOVA tests were applied to experimental data in bacterial distribution profiles to determine statistically significant differences among various data sets. Averages and standard deviations were estimated from four independent experimental runs for each data set. The tests were done in Prism 5.0a (GraphPad Software Inc.).

# 4 CF-μCHIP

# CHAPTER 4 CF-µCHIP

#### 4.1 Abstract

Chemotaxis was proven to be beneficial for the migration of degrading bacteria towards to industrial contaminant sources. Many studies demonstrated the importance of this microbial property under different circumstances; however, few quantitative analyses were done to measure the two essential parameters: chemotactic sensitivity coefficient  $\chi_0$ and chemotactic receptor constant  $K_c$ . It has been a challenging task to measure these parameters precisely, and no previous studies noticed that the coupling effect between  $\chi_0$ and  $K_c$  could prevent researchers from predicting the correct values, nor did they provide any way to solve this problem. This study used a multilayer microfluidic device and created a convection-free channel inside the chip by generating pressure balance at the two ends. Bacterial distribution in the channel was captured in terms of fluorescent intensity at steady state, and chemotactic bacterial distribution was compared with nonchemotactic mutant in presence of attractant at different concentrations, and more chemotactic population migrated into the channel at appropriate attractant concentration; the differences were statistically significant with p < 0.0001 by two-way ANOVA. The different attractant concentrations helped measure the correct value of  $K_c$ , and then  $\chi_0$ could be easily determined after fitting the chemotactic patterns with the correct  $K_c$  in the mathematical models. Both *Pseudomonas putida* and *Escherichia coli* strains were used, and the predicted chemotaxis parameters were consistent with the published results and the values derived from related work.

## 4.2 Introduction

The main purpose of this chapter is to present all the work on chemotaxis measurement that is done in the convection-free gradient generator (CF- $\mu$ Chip), and the essential content is about measuring the correct values of chemotaxis parameters: chemotactic sensitivity coefficient ( $\chi_0$ ) and chemotactic receptor constant ( $K_c$ ).

Section 4.3 summarizes all the experimental setup for this study, including the test on toluene absorbance in toluene, the device operating procedure and the fitting setup. Section 4.4 discusses all the main results from the CF- $\mu$ Chip. Fluorescein diffusion is studied on the time-lapse, and bacterial chemotaxis is quantitatively measured in presence of different attractant concentrations. Two different bacterial strains are tested and their corresponding chemotaxis parameters are calculated based on the results observed in the CF- $\mu$ Chip. Coupling effect between  $\chi_0$  and  $K_c$  is introduced and a feasible way is proposed to solve this problem. The results from this study are also compared with previous measurement to find a data relationship. Section 4.5 gives out the implication of the study on chemotaxis related topics.

# 4.3 Experimental Section

#### 4.3.1 PDMS Test with Toluene

Because PDMS is hydrophobic, and may absorb organic chemicals like toluene, a simple experiment was designed to test the absorbance in terms of the PDMS swelling ratio. 2 mM toluene solution in 10% RMB was prepared and then poured into a 10 mL amber glass bottle. 2 mM of toluene was selected as the test concentration because this was the largest concentration studied in the PDMS-based CF-uChip. Prior to exposure to toluene, the dimensions of three PDMS blocks were measured by a caliper, and the total weight was also recorded. The PDMS blocks were then put into the 2 mM toluenedissolved buffer and kept in the solution for three hours, and the total volume of the solution and the PDMS blocks depleted the gas phase so that there was no space for toluene to evaporate within the container. The glass bottle was sealed with screwed cap to prevent toluene from evaporating to the surrounding environment. Three hours was the longest time period to carry out toluene related experiments in the PDMS-based CF- $\mu$ Chip. After three hours, PDMS blocks were taken out and the dimensions were measured again. It was found that all dimensions had an average 0.1 % increase, and the total weight did not differ significantly from the original value (less than 0.0001 g increase from 0.6592 g). These results demonstrated that no significant absorbance of toluene happened to PDMS blocks during the three-hour experiment. We attributed this to the low concentration of toluene dissolved in water phase. Given these results we

decided that could be used as an adequate experimental material when 2 mM (or less) toluene solution was studied.

## 4.3.2 Experimental Setup

A time-lapse experiment using fluorescein solution  $(1.2 \times 10^{-4} \text{ M} \text{ dissolved in} 10\%$  Random Motility Buffer) was done to test the sensitivity and accuracy of the device based on the diffusion theory. Both the fluorescein solution (in light green color) and the buffer were injected into the device at the same flow rate of 1.0 mL/h, and immediately after the injection, images of the fluorescein diffusion in the cross channels were recorded through the microscope, and the diffusion profiles were plotted according to the distribution of fluorescence intensity.

Then bacterial suspension and attractant solution were injected through the two parallel inlets into the channel by a syringe pump (PHD 2000 Infusion, Harvard Apparatus) at a constant speed of 1.0 mL/h, which corresponded to 0.38 mm/s in the main channel and Reynolds number Re = 0.28. At this value of Re, the two streams satisfied the creeping flow criterion and diffusion was the only means of transport in the direction transverse to flow into the opening of the via.

A wide-field epifluorescent microscope (Olympus IX-70) with the  $2\times/0.05$  (Olympus, Plan) and  $20\times/0.40$  objective (Olympus, PlanFI) was used to observe the bacterial distribution within the channels. A dichroic filter (Chroma 51001 BS, double coated for DAPI and TRITC) was used to detect the *P. putida*'s fluorescence, and FITC and DAPI filters (Chroma 31013 602 NB) were used for *E. coli* strains, and FITC was also used for the fluorescein solution. Images about bacterial distribution were taken at

different locations across the cross channels. Then the bacterial fluorescence was normalized by the following equation:

$$I_{j}^{n} = \frac{I_{j} - I_{0}}{I_{F} - I_{0}}$$
 Eqn.4.1

*I* represents the light intensity from bacterial fluorescence and background noise, the superscript n stands for normalized value, subscript j stands for certain location point along the cross channel, 0 stands for the channel end with no bacterial input, and F stands for the other end with full bacterial density. Because the arc lamp source occasionally generates fluctuating light intensity, each I value was normalized in each image shot by dividing the background intensity from a plain area outside the channel.

# 4.3.3 <u>Mathematical Models</u>

One-dimensional mathematical models were used to evaluate the chemotactic parameters  $\chi_0$  and  $K_c$ , as diffusion only took place in the transverse direction. The directed migration of the bacterial population due to chemotaxis was represented by the chemotactic velocity,  $v_{ch}$ , (Chen et al., 1998). The expression of  $v_{ch}$  was simplified from the two dimensional Eqn 3.6 to

$$v_{Ch} = \frac{2}{3} v_b \tanh(\frac{\chi_0}{2v_b} \frac{K_c}{(K_c + a)^2} \frac{\partial a}{\partial x})$$
 Eqn 4.2

As indicated by Eqn 4.2, the chemotactic receptor constant links the concentration of the external chemical stimulus with the chemosensory system.

The chemoattractant gradient in Eqn 4.2 was calculated from the governing equation for the chemoattractant (Eqn 3.3). Because the system was convection free, the convection terms were canceled, then Eqn 3.3 was simplified to have the formulation of Fick's Second Law:

$$\frac{\partial c}{\partial t} = D \frac{\partial^2 c}{\partial x^2}$$
 Eqn 4.3

where *D* is the diffusion coefficient for either bacteria or attractant, and *c* stands for the concentration for either bacteria or attractant. The boundary conditions for the concentration profile in time and space, c(x, t), are  $c(0, t) = c_B$  and  $c(L, t) = c_0$ , and the initial condition is c(x, 0) = 0. The solution has a functional form that depended on the error function:

$$\frac{c_0 - c}{c_0 - c_B} = erf\left(\frac{x}{2\sqrt{Dt}}\right)$$
 Eqn 4.4

where  $c_0$  is the concentration at the matter's source and  $c_B$  is the concentration at the end of the diffusion space, and in this case,  $c_B$  is zero since there is no bacteria/attractant at the other end of channel, so the error function solution could be further simplified. Because the measurement took at the steady state, so the time term on the left hand side of the governing equation (Eqn 3.3) was canceled too. Also, since the diffusion happened in a bulk solution, porosity,  $\varepsilon_p$ , equals to 1, so  $D_{e,a}$  equals to  $D_a$ . Then the onedimensional equation was simplified to

$$0 = D_a \frac{\partial^2 a}{\partial x^2}$$
 Eqn 4.5

The ordinary differential equation could be easily solved and  $a(x) = a_0 \left(1 - \frac{x}{L}\right)$ , where *L* is the channel length, so concentration profile of attractant should be linear in the channel. Similarly, the governing equation used for bacterial density, *b*, was simplified to

$$0 = \mu_0 \frac{\partial^2 b}{\partial x^2} - \frac{\partial}{\partial x} (v_{Ch} b)$$
 Eqn 4.6

where  $\mu_0$  is the bacterial random motility, namely  $D_b$  in Eqn 3.5, with b(0) = 0 and  $b(L) = b_0$ .

#### 4.4 **Results and Discussion**

Fluorescein solution was used to determine how well the device worked based on diffusion time in the cross channel. Bacterial distributions of both *P. putida* and *E. coli* strains were observed and quantified to measure corresponding chemotaxis parameters. The coupling effect between chemotactic sensitivity coefficient  $\chi_0$  and chemotactic receptor constant  $K_c$  was studied and analyzed based on mathematical modeling tools. Generally speaking, errors in fitted values of  $\chi_0$  and  $K_c$  may compensate for each other. This was an essential factor that was omitted by many previous quantitative researches on bacterial chemotaxis, and this study introduced a straightforward method to solve the problem created by coupling effect.

### 4.4.1 Fluorescein Test

As shown in Figure 4.1, both the fluorescein solution (in light green color) and the buffer were injected into the device at the same flow rate of 1.0 mL/h, and a distinct interface formed between the two streams in the channel. Immediately after the injection, images of the fluorescein diffusion in the cross channels were taken by the microscope at different time points (Figure 4.2), and the diffusion profiles were plotted according to the distribution of fluorescent intensity in an hour observation (Figure 4.3).



**Figure 4.1** Illustration of the injection of both the fluorescein solution (light green color) and the 10% Random Motility Buffer at the same flow rate.



Figure 4.2 Time-lapse distribution of fluorescein solution in the cross channel at times of (a) 0

min, (b) 3 min, (c) 10 min, (d) 40 min and (e) 60 min.



**Figure 4.3** Normalized fluorescence of fluorescein within the cross channel at 3, 10 and 60 min. The black curves are the calculated distributions according to the error function solution from Eqn 3.5 using a published value for fluorescein diffusivity of  $0.49 \times 10^{-9}$  m<sup>2</sup>/s (Rani et al., 2005). The coefficient of determination R<sup>2</sup> is 0.99.

As shown in Figure 4.3, the concentration profile of fluorescein reached steady state within 60 minutes from the time of injection, and formed a linear distribution. Fitting curves were superimposed based on the error function solutions from Eqn 3.5 and matched the experimental data well using a diffusion coefficient of fluorescein at 0.49 ×  $10^{-9}$  m<sup>2</sup>/s, which was reported by Rani et al. (2005). The Einstein relation  $t = \frac{L^2}{2D}$  was used to estimate the time to reach steady state, where *L* was 1.5 mm and *D* was  $0.49 \times 10^{-9}$ 

 $^{9}$  m<sup>2</sup>/s. The calculation indicates that a time *t* of 40 minutes is sufficient for the fluorescein distribution to reach steady state in the channel, which is consistent with the results from the model equations.

# 4.4.2 <u>Measurement of Bacterial Chemotaxis</u>

The precise measurement and prediction of fluorescein distribution demonstrated the feasibility to observe bacterial distribution in the CF- $\mu$ Chip. Distributions of chemotactic bacteria in the presence of a linear attractant gradient were then studied in this microfluidic device. Table 4.1 summarizes the time to reach steady state for different bacterial strains and attractants as calculated from the Einstein equation. All bacteria and chemoattractant chemicals achieved steady state within an hour of injection, except for *E. coli* HCB1, which required 1.3 hours. Based on these predicted results, the observation start point was chosen to be two hours after the injection for *P. putida* strains and *E. coli* HCB437, and four hours after the injection for *E. coli* HCB1, in order to ensure the establishment of a steady state system. Figure 4.4 shows an image of *E. coli* HCB1 cells within a single cross channel of the CF- $\mu$ Chip at several times. Note that the diffusion profile did not appear to change very much between two and four hours.

**Table 4.1** Calculated time to reach steady state for all bacterial strains and chemicals used in the CF-µChip

Ran	dom Motility ( $\mu_0$ ) or Diffusion	Time to Reach Steady
С	Coefficient $(D_a) [\times 10^{-10} \text{ m}^2/\text{s}]$	State [hour]
<i>P. putida</i> F1	13	0.24
---------------------	-----	------
P. putida F1 CheA	13	0.24
<i>E. coli</i> HCB1	2.4	1.30
E. coli HCB437	17	0.18
Toluene	9.5	0.33
α-methylaspartate	8.6	0.36



**Figure 4.4** Bacterial distribution (*E. coli* HCB1) within a cross channel at different times. The gray level intensity in the image corresponds to the bacterial density.

Bacterial suspension and attractant solution were then injected into inlets on opposite sides and formed two parallel streams. The *P. putida* distribution in the presence

of toluene at steady state is shown in Figure 4.5 and 4.6. In the absence of a chemotactic response, the governing equation for bacterial distribution at steady state has the same form as that for an attractant (Eqn 4.3), which means that the bacterial density also follows a linear distribution with a constant gradient in the cross channel, as shown by both the experimental data (red points) and the fitting result (red line) of the nonchemotactic mutant (P. putida F1 CheA) in Figure 4.6. For chemotactic bacteria P. *putida* F1 in the presence of a concentration gradient of attractant, the advective term induced by chemotaxis in the governing equation (Eqn 4.4) caused more bacteria to migrate into the cross channel from the parallel flow channel. As a result, the bacterial distribution deviated positively from the linear distribution and formed a parabolic shape, as shown by the blue and orange curves in Figure 4.6. The extent of deviation was determined by the strength of the chemotactic response as well as the attractant concentration of the local environment. In Figure 4.6, the data points in both blue and orange groups were collected from the chemotactic *P. putida* F1. The difference was a different attractant concentration introduced at the opposite end of the cross channel: the toluene concentration used for the blue diamonds was 2 mM, and that for the orange triangles was 0.2 mM. A two-way ANOVA test showed that the difference was statistically significant between the two chemotactic experiments (2 and 0.2 mM) with p < 0.0001, the difference was also significant between the 2 mM and nonchemotactic control with p < 0.0001, but the difference between the 0.2 mM and the control was not statistically significant.



**Figure 4.5** The images of *P. putida* distribution in a cross channel at steady state. The gray level intensity represents the bacterial density. The distribution of *P. putida* F1 is observed in presence of (a) 2 mM toluene as the attractant at the opposite side, and (b) 0.2 mM toluene, and (c) the distribution of *P. putida* F1 CheA is also recorded in presence of 2 mM toluene.



**Figure 4.6** *P. putida* distribution in the cross channel of CF-µChip at steady state. Attractant diffuses from left to right in the figure, and its concentration is 2 mM for the blue diamond data and 0.2 mM for the orange triangles. Experimental results of bacterial density are plotted as dots (nonchemotaxis in red), and the corresponding lines are the fitting results.

The rationale for choosing these two particular concentrations will be discussed in the following section about decoupling the effect of the chemotaxis parameters. In some previous work (Olson et al., 2004; Lanning et al., 2008; Law and Aitken, 2005; Wang et al., 2012) just one attractant concentration was tested, and because the chemotactic sensitivity coefficient,  $\chi_0$ , and chemotactic receptor constant,  $K_c$ , could compensate for each other in the expression of chemotactic velocity (Eqn 4.2), it was necessary to estimate a value for one of the parameters (usually  $K_c$ ) in order to fit the other. In this study experiments were conducted with two different attractant concentrations. Ford and Lauffenburger (1991) checked the relationship between  $\chi_0$  and a series of attractant concentrations using stopped-flow diffusion chamber (SFDC), and found that  $\chi_0$  was independent on the attractant concentration. The work in the dissertation was a follow up of this idea using a different experimental system. The new experimental system (CFµChip) allowed to observing bacterial distribution at steady state, while SFDC detected the bacterial density as a function of time, so CF-µChip eliminated the possible effect of time during measurement. Experiments with the 2 mM toluene source attracted more chemotactic bacteria into the cross channel than the 0.2 mM one, as the area under the distribution curve in blue was greater than the one in orange. This result also indicated that the correct  $K_c$  for *P. putida*/toluene was the same order of magnitude as 2 mM. Furthermore, the value of  $K_c$  was within the range of previously reported values for similar chemical contaminants, 0.001 to 1 mM (Parales et al., 2000).

The qualitative experimental results were further supported by the quantitative comparison to model equations at both attractant concentrations. Fitting curves indicated that only a  $K_c$  value near 1 mM could match the experimental results at both toluene concentrations in Figure 4.6. The fitting results indicate that the chemotactic sensitivity coefficient  $\chi_0$  is  $1.8\pm0.7 \times 10^{-4}$  cm<sup>2</sup>/s, and chemotactic receptor constant  $K_c$  is  $1\pm0.4$  mM. The value of  $\chi_0$  is in the same magnitude as the average value for *P. putida* F1 to TCE ( $5.4 \times 10^{-4}$  cm<sup>2</sup>/s), and  $K_c$  is also same as the reported value for *P. putida* F1/TCE at 1 mM (Olson et al., 2004). Moreover, because  $K_c$  represents the optimal concentration for the chemotactic bacteria to accumulate, the greatest difference between chemotactic and

nonchemotactic bacterial accumulations when toluene concentration is 2 mM occcurs at the midpoint of the graph, where the toluene concentration is close to 1 mM. Figures 4.7 and 4.8 show results similar to Figures 4.5 and 4.6, but using a different bacterial strain. The chemotactic wild type is *E. coli* HCB1 and the nonchemotactic control is HCB437 (smooth-swimming mutant), and the chemoattractant is  $\alpha$ -methylaspartate. Modeling fits to experimental data show that  $\chi_0$  is  $2.4\pm0.5 \times 10^{-4}$  cm<sup>2</sup>/s and  $K_c$  is  $0.13\pm0.03$  mM, both supported by previous work (Lewus and Ford, 2001). One interesting fact is that  $K_c$  for *E. coli* is almost an order of magnitude lower than *P. putida*, and the largest differences between chemotactic and nonchemotactic bacteria occurs when the initial attractant concentration is approximately equal to the value of  $K_c$ .



**Figure 4.7** The images of *E. coli* distribution in a cross channel at steady state. The gray level intensity represents the bacterial density. The distribution of *E. coli* HCB1 is observed in presence of (a) 3 mM  $\alpha$ -methylaspartate as the attractant at the opposite side, and (b) 0.3 mM  $\alpha$ -methylaspartate, and (c) the distribution of nonchemotactic *E. coli* HCB437 is also recorded in presence of 3 mM  $\alpha$ -methylaspartate.



**Figure 4.8** *E. coli* distribution in the diffusion-only channel at steady state. Attractant diffuses from left to right in the figure, and its concentration at the left-hand side is 0.3 mM for the blue diamond data and 3 mM for the orange triangles. Experimental results of bacterial density are plotted as symbols (nonchemotaxis in red), and the corresponding lines are the fitting results.

# 4.4.3 Independent evaluations of $\chi_0$ and $K_c$

One essential problem that was omitted by previous studies was the coupling effect between  $\chi_0$  and  $K_c$ . Ford and Lauffenburger investigated the values of  $\chi_0$  over a range of initial attractant concentrations in SFDC, and found  $\chi_0$  was independent on the change of the attractant concentration. The effect of  $K_c$  on bacterial distribution was still not explicitly studied in presence of different attractant concentrations, and we found that this new topic about  $K_c$  was important to inspect in order to obtain accurate values of  $\chi_0$ and  $K_c$ . Figure 4.9 illustrates results for different combinations of  $\chi_0$  and  $K_c$  values that yield similar curves for bacterial distribution in the cross channel. Table 4.2 lists the wide range of values for the chemotaxis parameters used to generate the simulation curves in Figure 4.9.



**Figure 4.9** Similar simulation curves resulted from the combinations of different  $\chi_0$  and  $K_c$  values.

**Table 4.2**  $\chi_0$  and  $K_c$  values used for the different simulation curves in Figure 4.9.

	$\chi_{\theta} [\times 10^{-8} \text{ m}^2/\text{s}]$	$K_c$ [mM]
Sim 1	36	0.01

Sim 2	3.6	0.1
Sim 3	1.8	1

As shown in Table 4.2, even as the value of  $K_c$  was increased from 0.01 to 1 mM, the simulation curves resulted in nearly the same bacterial distribution by an appropriate decrease in  $\chi_0$ . Many of the previous studies related to chemotaxis (Olson et al., 2004; Lanning et al., 2008; Law and Aitken, 2005; Wang et al., 2012) assumed a value for  $K_c$ based on published values and then determined  $\chi_0$  by a curve-fitting exercise. However, the reported  $K_c$  values were specific to certain bacteria/ attractant pairs; in order to apply appropriate values of  $\chi_0$  and  $K_c$  to a different bacteria/attractant pair, a direct measurement of  $K_c$  for the pair of interest was needed. The effect that each parameter has on the bacterial distribution when varied independently of the other is illustrated in Figures 4.10 and 4.11. The default value for  $\chi_0$  was set as  $1 \times 10^{-8}$  m<sup>2</sup>/s and  $K_c$  as 0.1 mM for both figures.

Figures 4.10 (a) and (b) show the normal changes of  $\chi_0$  and  $K_c$  in the cross channel with the attractant concentration of 2 mM. In other words, the increase in either  $\chi_0$  or  $K_c$  could increase the bacterial population in the channel, which explained why the fitting curves overlapped each other over a wide value range of  $\chi_0$  and  $K_c$ .



**Figure 4.10** Simulated results of the impact of changing  $\chi_0$  and  $K_c$  on bacterial distribution in presence of 2 mM of chemoattractant. The default value for  $\chi_0$  was set as  $1 \times 10^{-8}$  m<sup>2</sup>/s and for  $K_c$  as 0.1 mM, and (a) shows the impact of  $\chi_0$  with a fixed  $K_c$  at the default value, and (b) shows the impact of  $K_c$  with a fixed  $\chi_0$  at the default value.

By performing the experiment or simulation at two different attractant concentrations, it was possible to evaluate both parameters, independently. Figure 4.11 shows results for the simulation in the Figure 4.10 at a lower attractant concentration of 0.2 mM. While the  $\chi_0$  value still showed a positive influence on bacterial population in the channel, the impact of  $K_c$  did not follow the same trend as the results from the higher level of attractant concentration. As shown by Figure 4.11 (b), the middle  $K_c$  value of 0.1 mM resulted in the most bacterial population in the channel, and 1 mM resulted in the least. This was because that the attractant concentration of 0.2 mM covered the optimal locations for chemotactic bacteria with  $K_c$  of 0.1 mM in its concentration gradient; however, bacteria with  $K_c$  of 1 mM could not find their optimal location in this concentration gradient started from 0.2 mM. In other words, the correct  $K_c$  could be determined first by tailoring the concentration gradient of attractant to a certain range, and  $\chi_0$  could then be fitted using the specific  $K_c$ . Therefore, the coupling effect between the two chemotaxis parameters could be solved.



**Figure 4.11** Simulated results about the impact of changing  $\chi_0$  and  $K_c$  on bacterial distribution in presence of 0.2 mM of chemoattractant. The default values for  $\chi_0$  is set as  $1 \times 10^{-8}$  m<sup>2</sup>/s and  $K_c$  as 0.1 mM, and (a) shows the impact of  $\chi_0$  with a fixed  $K_c$  at the default value, and (b) shows the impact of  $K_c$  with a fixed  $\chi_0$  at the default value.

#### 4.4.4 <u>Comparison with previous *K<sub>c</sub>* measurement</u>

Brashear (2009) measured the chemotactic receptor constant,  $K_c$ , of *P. putida* F1 to benzoate using an agarose plug assay. The methodology for this experiment and its data analysis are summarized in the Appendix. Plug assays were prepared following the procedure from Yu and Alam (1997), and the setup is shown in Figure 4.12. The central agarose plug contained a specific attractant concentration and was surrounded by a bacterial suspension containing a  $10 \times$  lower attractant concentration. The plug concentrations ranged from  $10^{-6}$  to  $10^{-1}$  M. Bacterial accumulation in vicinity of the central plug was observed under the microscope and the  $K_c$  value was determined from the geometric average concentration, which elicited the greatest accumulation of bacteria.



**Figure 4.12** Agarose plug assay diagram with (a) top view and (b) side view (Courtesy of Brashear).

Brashear and coworkers (unpublished data) found that *P. putida* F1 accumulation in presence of benzoate at different concentrations followed a bimodal distribution, as shown in Figure 4.13. The two corresponding peaks in the figure indicated the two distinct values of  $K_c$ . The peak in accumulation on the right hand side of the figure as represented by the model curve indicated that  $K_{c,high}$  was 0.95 mM, and the lower peak in accumulation on the left hand side of the figure indicated that  $K_{c,low}$  was 0.0027 mM. The coexistence of  $K_{c,high}$  and  $K_{c,low}$  was supported by experimental findings and mathematical models for two receptor subpopulations (Clarke and Koshland, 1979; Ford and Lauffenbruger, 1991). The two different receptor sites might interact with the same stimulus molecules with different affinity capacities: one showed a low affinity to the attractant at a high external attractant concentration ( $K_{c,high}$ ), and the second receptor corresponded to a high affinity at a low attractant concentration ( $K_{c,low}$ ). The attractant concentration corresponding to  $K_{c,high}$  was 3 mM in the plug and 0.3 mM in the surrounding bacteria solution, and the attractant concentration corresponding to  $K_{c,low}$  was 0.008 mM in the plug and 0.0008 mM in the surrounding bacteria solution. These values were within the typical range for chemotactic receptor constant,  $K_c$ , from 1 × 10<sup>-6</sup> M to 1 × 10<sup>-3</sup> M (Dahlquist et al., 1972; Ford and Lauffenbruger, 1991; Jasuja et al., 1999).



**Figure 4.13** Chemotactic response of *P. putida* F1 to sodium benzoate at different concentrations in agarose plug assay (Brashear, 2009).

The results of *P. putida* F1 accumulation to toluene were compared with Brashear's work that was discussed above. Toluene and benzoate have many similarities. First of all, they are both simple aromatic components. Secondly, they are both chemoattractants to *P. putida* F1 (Parales et al., 2000) and are degradable to this bacterial strain. More importantly, evidence shows that the broad-substrate-specificity chemoreceptors may exist in *P. putida* F1 to detect a variety of aromatic hydrocarbons, including toluene and benzoate (Parales et al., 2000).

Besides the similarities between toluene and benzoate, the two experimental systems shared some common features. Both the plug assay and CF-µChip were designed to look at the bacterial distribution in presence of a constant attractant source in which a

predictable concentration gradient was formed. One difference was that the bacterial distribution in CF-µChip was measured at steady state, while it was measured at unsteady state in plug assay. Although the measurement was taken at unsteady state in plug assay, the time points to record the images were the same among all the experimental trials, so there was no time variable affecting the bacterial distribution at different attractant concentrations. Another difference was that the plug assay had a 10 times diluted attractant concentration in the surrounding bacterial suspension, but the attractant concentration was zero for the bacterial end in CF-µChip. In order to test if this difference could be neglected, fitting of bacterial distribution was then done by modifying the toluene concentration to 0.2 mM at the bacterial end, while the other end was still 2 mM. Figure 4.14 shows the comparison of bacterial distribution between the new and the old assumption on attractant concentration at the bacterial end. The two simulated bacterial distributions had a similar trend, and the biggest difference between them was only approximately 4 %, which could be neglected compared to the overall bacterial population. Therefore, the benzoate related data from plug assay and the toluene related data from CF- $\mu$ Chip were compared and plotted together in Figure 4.15. The density differences between chemotactic and nonchemotactic bacteria were calculated based on both the experimental and simulation data, and were compared with part of Brashear's data at specific attractant concentrations, with the maximum value in bacterial density normalized to 1 and the geometric mean concentration in Figure 4.13 converted to the attractant concentration in the plug.



Figure 4.14 (a) Simulation of chemotactic bacterial distribution with different attractant

concentration at the bacterial end. The solid curve is generated from the zero attractant background, and the dashed curve is from the background with the diluted attractant concentration at the bacterial end. (b) The differences between the two curves in (a) along the channel direction.



**Figure 4.15** Comparison between the benzoate related data (open triangle) from plug assay and the toluene related data (solid square) from CF- $\mu$ Chip. The black line connects the fitting data for bacterial distribution to toluene.

The toluene related data only covered the range of attractant concentration from 0.05 to 1 mM, and benzoate related data points in this range matched exactly with the toluene related trend. In addition, both studies provided a  $K_c$  value of around 1 mM. All these findings indirectly suggest the possibility of the earlier statement: broad-substrate-

specificity chemoreceptors may exist in *P. putida* F1 to detect a variety of aromatic hydrocarbons, including toluene and benzoate. However, this study did not find enough evidence for  $K_{c,low}$  at a lower attractant concentration; the  $K_{c,low}$  might only exist for benzoate, or its induced accumulation was concealed by the limited precision in measurement. More studies targeting the lower concentration ranges can be done to test the possibility of  $K_{c,low}$ 's existence for *P. putida* and other bacterial strains. The same experimental procedure is suggested except using a lower initial toluene concentration close to the reported value of  $K_{c,low}$  at 0.0027 mM, and a fitting showed (data not shown) that parabolic bacterial distribution is similar to the one for *P. putida* F1 at 2 mM toluene (Figure 4.6) under the condition of this low attractant concentration.

#### 4.5 Implications

Using the convection-free channel, an accurate methodology was established to evaluate the essential chemotaxis parameters, chemotactic sensitivity coefficient ( $\chi_0$ ) and chemotactic receptor constant ( $K_c$ ). Many combinations of chemotactic bacteria and attractants can be tested in the system under different initial attractant concentrations, as long as the attractants do not interact or react with the PDMS material. Combinations of two different attractants/repellents can also be studied by introducing each chemical component into one end of the cross channel. In summary, this methodology can enrich the current database of chemotaxis parameters to a great extent, and is highly recommended to become a common procedure to quantitatively evaluate bacterial chemotaxis. Bacterial random motility and chemical diffusion coefficient can also be measured in this device. The preciseness of the measurement needs to be improved in future studies; the enhancement of bacterial fluorescence and the reduction of arc lamp noise are considered as the two main aspects for a more accurate signal detection.

# **5** Η-μCHIP

# CHAPTER 5

# Η-μСΗΙΡ

#### 5.1 Abstract

Nonaqueous phase liquid (NAPLs) contaminants are difficult to remove from groundwater due, in part, to the heterogeneous structure in soil. Chemotaxis toward the chemical pollutants, which they degrade, provides a mechanism for bacteria to migrate to locations of high contamination, which may enhance the overall effectiveness of bioremediation. Chemotactic effect on bacterial abundance was studied within the low permeable NAPL-contaminated region in a well-defined porous medium. A heterogeneous microfluidic device was designed to mimic features of the natural contaminated groundwater system. In order to achieve the goal, a new method was developed to trap NAPL residuals (toluene) in low permeable zones, and bacteria were injected into the system with groundwater flow in highly permeable pathways. Chemotactic bacteria (P. putida F1) migrated preferentially towards and accumulated in the vicinity of NAPL contaminant sources. The accumulation of chemotactic bacteria was 15% more by comparison to nonchemotactic controls (P. putida F1 CheA). Bacteria in the device were also subjected to different flow rates within typical range of groundwater flow rates. Chemotactic bacteria had a generally 5% more accumulation at 0.5 m/d near the intersection between the horizontal channel and the porous network than both the nonchemotactic mutant and bacterial distribution at 5 m/d. The breakthrough curves observed at the outlet provided indirect evidence that chemotactic bacteria intended to retain in contaminated and low permeable region for a longer time than the nonchemotactic bacteria at 0.25 m/d. A higher flow rate at 5 m/d diminished this retention due to chemotaxis. Mathematical models and related computational fittings yielded outcomes that were consistent with the experimental results, and statistical analysis also supported the experimental comparisons. There is no direct observation on biodegradation, but because toluene is degradable by *P. putida* F1, the experimental observations of biased accumulation of chemotactic bacteria around the NAPL sources within the low permeable region will lead to an increase of contaminant consumption, which can improve the efficiency of bioremediation.

# 5.2 Introduction

The main purpose of this chapter is to present all the results achieved in the heterogeneous porous microfluidic device (H-µChip).

Section 5.3 summarizes all the experimental setup for this study, including the process for trapping toluene droplets in the low permeable region, the device operating procedures and the fitting setup. Section 4.4 discusses all the main results from the H-

 $\mu$ Chip. Toluene ganglia are trapped in designated locations of the porous network as contaminant sources, and *P. putida*'s chemotactic response to this chemoattractant is studied under three different circumstances. Firstly, accumulation induced by bacterial chemotaxis is observed at the intersection area between the porous network and the horizontal channel at different flow rates, which indicates a biased movement of chemotactic bacteria toward the contaminant sources. Secondly, bacterial chemotaxis was observed in the vicinity of toluene ganglia under no flow condition, and this result provided direct evidence of chemotaxis to NAPL component in porous structure, and in addition, this experimental setup can be used as an alternative method for NAPL study in agarose plug assay. Thirdly, the breakthrough curves of chemotactic and nonchemotactic bacteria are compared in the H- $\mu$ Chip under different flow rates. In section 4.5 the implication of the study on in-situ bioremediation is discussed.

#### 5.3 Experimental Section

#### 5.3.1 Bacteria/Attractant System

*Pseudomonas putida* and toluene was the model system for chemotaxis toward a NAPL attractant. As a brief summary from Chapter 3 Materials and Methods, *Pseudomonas putida* F1 (wild type) was obtained from C. S. Harwood (Parales et al., 2000) and nonchemotactic mutant *P. putida* F1 CheA from R. E. Parales (Liu et al., 2009). An aliquot (300 μL for *P. putida*) of frozen stock at -80 °C was used to inoculate 100 mL of the modified Hutner's Mineral Base in a sealed 200 mL glass bottle. 30 μL toluene was added as the carbon source for bacteria into the gas phase of the growth media. Oxygen (GT&S, oxygen compressed USP) was injected at 5 psi for 10 minutes to ensure a sufficient supply. When the optical density (measured at 590 nm in Beckman Coulter, DU 730) reached 0.80 (corresponding to the mid-exponential phase of growth), bacteria were harvested and resuspended in 10% Random Motility Buffer (RMB) to a density similar to the one when harvested.

*P. putida* F1 was then dyed with the vital membrane stain FM 4-64 (Invitrogen) at a concentration of 5  $\mu$ g/mL for 10 minutes and F1 CheA was dyed with 100 mg/L DAPI (Invitrogen) for 30 minutes, and both bacterial suspensions were washed twice and then mixed for later experimental use. The bacteria suspension was also mixed with 1.2 mM sodium nitrate (Sigma-Aldrich, ACS reagent) as electron acceptor to maintain bacterial motility (Bauer et al., 2008). 7 mL pure toluene (Sigma-Aldrich, HPLC grade) was dyed with 1 mg Oil Red O (FisherBiotech, electrophoresis grade) to show observable red color.

# 5.3.2 <u>Toluene Trapping</u>

70% ethanol (LabChem Inc., 70% v/v reagent) was first injected into the microfluidic device from both the bacterial and NAPL inlets, in order to saturate the system. Because air is soluble in ethanol, the air bubbles in the system were eliminated quickly by continuous high-pressure ethanol flow. DI water was then injected into the microfluidic device to displace the ethanol, and the microfluidic system was kept saturated during the whole experiment. Red dyed toluene was injected from the NAPL inlet at the bottom of Figure 5.1 to replace the water in the fine network, and then DI water was injected again to wash out the toluene in the fine network, while toluene droplets remained in all the ganglia, as illustrated in Figure 5.1.



**Figure 5.1** Schematic illustration of the bacterial injection in H- $\mu$ Chip. The red color represents the toluene ganglia, and the arrows indicate the inlet, the outlet and the flow direction for bacteria.

# 5.3.3 <u>Continuous Injection</u>

The bacterial suspension was injected into the main channel by 100  $\mu$ L point-style syringes (Spectrum Laboratory Products Inc.), and then the syringes were fixed onto a syringe pump (PHD 2000 Infusion, Harvard Apparatus) and pushed at different speeds, which were comparable to 0.5 and 5 m/d in the main channel.

This study was conducted to examine the bacterial distribution at the interface between the horizontal channel and the porous network at the different flow rates, 0.5 and 5 m/d. Quantitative analyses were made for comparisons between different flow rates, and between chemotactic and nonchemotactic bacteria. These two different values of flow velocity were chosen because they are within the typical range of groundwater flow rate from 0.1 to 10 m/d, and each of the values can be representative of the slow and fast flows, respectively. Bacterial suspension was continuously injected at certain flow rate. Preliminary simulation showed that the system reached the steady state after two hours of injection at 0.5 m/d, and after half an hour at 5 m/d based on Brinkman equation and advection-dispersion equations (Eqn 3.2-3.4). Images on bacterial fluorescence were also taken in all the channel spaces at the time points as mentioned above, and results showed that bacteria occupied all spaces after two hours at 0.5 m/d and half an hour at 5 m/d, and the densities in the horizontal wide channel were the same as those in the thin channels deep in the porous network. This observation was done with unstained bacteria, and the unstained bacterial density was recorded as the intensity of scattered light from bacteria in bright field; this method was described in details and validated by Wang et al. (2012). This study was done in the original H- $\mu$ Chip, which was shown in Figure 2.6. Because the device had eight opening junctions at the interface between the porous network and the horizontal channel, so bacterial density at each of the junctions was recorded in terms of light intensity. The predicted distribution of attractant concentration in the horizontal channel of the original H- $\mu$ Chip was compared with that in the new H- $\mu$ Chip (Figure 5.1), and the attractant concentrations were compared along the centerline of the horizontal channel and three evenly distributed transverse lines, as indicated by the red lines in Figure 5.2. The positions of the transverse lines corresponded to three openings between the horizontal channels and the porous matrix in the original design.



**Figure 5.2** The predicted attractant concentrations for both the original and the new H- $\mu$ Chip in the horizontal channel were compared along the red lines in the image.

# 5.3.4 <u>No Flow</u>

The flow stopped when bacterial density in porous network equaled to that in main channel by visual observation, and after the whole system became stationary for 10 minutes, the bacterial distribution in vicinity of the toluene ganglia was recorded under the microscope. This step mimicked the protocol to observe *P. putida* distribution in plug assay (Toepfer et al., 2012). 30 images were taken in different channels of the porous network near the edge of ganglia, and then were averaged for image analysis.

# 5.3.5 Breakthrough Trends

The other study was to wash out the bacteria mixture at the different flow rates, 0.25 and 5 m/d. These two different values of flow velocity were chosen because they are

within the typical range of groundwater flow rate from 0.1 to 10 m/d, and each of the values can be representative of the slow and fast flows, respectively. Then the injectate fluid was changed from bacteria to 10% random motility buffer, and the speed was reduced to 0.25 or 5 m/day to wash the bacteria out of the microfluidic device for 18 continuous hours. Images of the fluorescent bacteria at the outlet were taken and collected during this process. Bacterial density was then recorded in term of fluorescent intensity at different time points, and was normalized with initial intensity in the main channel at certain speed. Observation was done at the outlet of the main channel. The image analysis for both studies followed the same protocol in Wang et al. 2012.

#### 5.3.6 <u>Fitting Setup</u>

The two-dimensional profiles of flow and attractant/bacterial distribution were solved using Equation 3.2 - 3.6. The equations and boundary conditions might subject to slight changes for different experimental requirements.

# 5.4 Results and Discussion

# 5.4.1 <u>Toluene Trapping</u>

Red dyed toluene was injected from the NAPL inlet to replace water within the fine network and ganglia, and then DI water was injected again to wash out toluene in the fine network, while toluene remained within the ganglia, as shown in Figure 5.3.



**Figure 5.3** Toluene dyed with Oil Red O was retained as ganglia in the microfluidic device. A light blue colored aqueous solution was also injected to illustrate the channel patterns.

The entrapment of toluene ganglia resulted mainly from the different physical properties between the material and the NAPL chemical: glass (the material of the device) is hydrophilic and toluene is hydrophobic. Therefore, toluene exhibits a high contact angle in the water saturated glass-based spaces and keeps a round intact shape. When water washes toluene out of the porous structure, it flows along the glass surface because both water and glass are hydrophilic, so the toluene residuals in the channels can be carried away by water flow easily due to the their poor attachment to the glass surface; however, the toluene ganglia are difficult to wash out As shown in Figure 5.4 as a

horizontal view of Figure 3.1c, a thin layer of water surrounds the toluene ganglion, and the toluene ganglion exhibits a high surface tension at the top openings, which generates an overall downward force  $F_s$  on the ganglion. Moreover, the glass wall on top also provides a downward resistance force  $F_w$  on the toluene ganglion, and both forces prevent the organic compound from being washed out. Thus, even though toluene has a lower density than water, toluene remains as ganglia in the bottom layer of the device. This method of trapping NAPL based on surface tension and device's hydrophilicity is new achievement. Wan and Wilson (1994a) successfully retained NAPL in a porous medium, but it was achieved in an unsaturated system and the entrapments were randomly distributed, so the bacterial distribution could be highly affected by adjacent NAPL sources and air bubbles. The method introduced by this study could retain NAPL ganglia in the designated spaces of the saturated porous network, which helped quantify chemotaxis effect toward single NAPL attractant source, and can be widely used in the trapping of nonaqueous phase liquid chemicals in future research.



**Figure 5.4** Cartoon illustration of the toluene entrapment in H- $\mu$ Chip. F<sub>s</sub> stands for the force vector induced from surface tension on a toluene ganglion, and F<sub>w</sub> represents the resistance force from the glass wall.

After toluene ganglia were trapped within the circular spaces of the device, a high flow rate was used to test their stability. The toluene ganglia remained stable under injection rates comparable to 100 m/d in the main channel and after 24 hours of continuous flow at 5 m/d. This high level of stability of the toluene ganglia is attributed to the low solubility (5.6 mmol/L) and high surface tension between toluene and water. By way of extension to natural systems, these two properties also impact NAPL retention as a pure phase and its distribution within the interstices of the soil matrix. Moreover, as the flow rate was further reduced within the narrow pore spaces, it was more difficult to wash out the residual NAPL. These are contributing factors to why NAPL contaminants remain in the groundwater system for decades.

#### 5.4.2 Bacterial Accumulation under Continuous Injection

The continuous injection method (Figure 5.1) simulated the actual bioremediation injection, which mainly happened at the high conductive region instead of low permeable layer in order to avoid clogging and built-up pressure (Gierczak et al., 2006; Lee et al., 2000). Because this experiment was carried out in the original H- $\mu$ Chip, in which the porous structure was coarser and the pores had a larger size (Figure 2.6), several preliminary simulation were conducted to test whether the results from the original H- $\mu$ Chip could be considered good indicators of expected behavior in the new device. The observation of bacterial accumulation with the original H- $\mu$ Chip occurred within the horizontal channel, so we compared the velocity field and attractant distribution within the horizontal channels of the two microfluidic devices. We reasoned if they were

comparable, then the results from the original H- $\mu$ Chip could be used to indicate what would also happen in the new H- $\mu$ Chip. As discussed in Appendix E, the velocity fields in the horizontal channel were almost exactly the same for both designs. A comparison of the attractant distributions is presented in Figure 5.5 and 6.6. Both attractant distributions followed a similar increase trend along the centerline of the horizontal channel. The increase was also nearly linear, and the attractant concentration for the new H- $\mu$ Chip was slightly lower than that for the original design at each location. This is because the finer porous structure helped to retain NAPL concentration, so that less of this chemical could be brought into the wide horizontal channel; this is also close to the real NAPL contamination problem, where NAPL residuals could remain in the fine porous media for decades. Although there was a slight difference in the attractant distribution, the ratio of the biggest difference value to the local concentration in the new H- $\mu$ Chip was only 4.3%, so the difference was fairly small on the horizontal direction.



**Figure 5.5** The simulated attractant distribution along the centerline in the horizontal channel for both the original (black) and the new (gray) H- $\mu$ Chip at 0.5 m/d.

Attractant distributions in the direction transverse to flow are compared in Figure 5.6. The distributions in different microfluidic devices at each position overlap each other. The location at 0 m corresponds to the intersection between the horizontal channel and the porous structure, and the bacterial distribution at each opening was observed in a 500  $\mu$ m by 500  $\mu$ m region of interest next to the intersection in the horizontal channel. Figure 5.6 shows that the trends follows linear distributions in the range of 0 to 500  $\mu$ m, and the slopes are also similar to each other. In fact, the averaged concentration at the openings in H- $\mu$ Chip is 4.6±0.4 % higher than that in the original design, which is also the largest difference at all locations, and the slopes from 0 to 500  $\mu$ m in H- $\mu$ Chip are 2.3±0.2 % higher than that in the original design. The chemotactic velocity is related to

this values, as describes in Eqn 3.6. If  $K_c$  is set as 1 mM for *P. putida* F1 and toluene, the calculated chemotactic velocity in H-µChip is approximately 2.1 % lower than that in the original design; the difference is relatively small and can be neglected. Overall, the attractant distributions had many similarities in the horizontal channel for both microfluidic devices, so a bacterial accumulation near the intersection in the original design could also indicate a similar accumulation in the new H-µChip, which might be a bit larger than the former because of the plateau problem in the former device.





The results about bacterial accumulation under continuous injection in the original H- $\mu$ Chip are shown in Figure 5.7 and 6.8. Chemotactic and nonchemotactic bacteria are compared in Figure 5.7, and chemotactic bacteria are compared at two different fluid velocities in Figure 5.8.



**Figure 5.7** Distribution of chemotactic (light gray square) and nonchemotactic (dark gray circle) bacteria at different junctions with a fluid velocity of 0.5 m/d. The connecting lines indicate the fitted data for accumulation of chemotactic bacteria at the junctions, and the fitted results for nonchemotactic bacteria respectively.



**Figure 5.8** Distribution of chemotactic bacteria at different junctions under different convective flow rates, which are 0.5 m/d (gray square) and 5 m/d (black triangle) respectively. The connecting lines indicate the fitted data for bacterial accumulation at the junctions with flow rate of 0.5 m/d, and the fitted results for that at 5 m/d respectively.

Greater accumulation of chemotactic bacteria was observed at all the junctions, when compared with nonchemotactic bacteria, as indicated in Figure 5.7. This figure also shows that the distribution of both chemotactic and nonchemotactic bacteria followed the trend predicted by the mathematical models with the parameters fitted from the previous chapter, which are listed in Table 6.1. The accumulation of chemotactic bacteria near the junctions decreased at a higher convective flow rate of 5 m/d (Figure 5.8), which is supported by the previous experimental results (Wang et al., 2012); Wang and coworkers reported that a transverse bacterial accumulation was observed in the vicinity of a NAPL
interface at the slow flow rate of 0.5 m/d (5.8  $\mu$ m/s), which is smaller than the bacterial swimming speed of 44  $\mu$ m/s, but the accumulation decreased dramatically when the flow rate increased to 5 m/d, which is higher than the bacterial swimming speed. A smaller convective flow left more retention time for the motile bacteria to react to the attractant source on the transverse direction. All experimental data were compared statistically with two-way ANOVA test, and the test showed that the chemotaxis group at 0.5 m/d is significantly different from either the nonchemotaxis control or the chemotaxis group at 5 m/d, with a p value smaller than 0.0001 in both cases. Such difference was not found when the nonchemotaxis group was compared with the 5 m/d group with p = 0.1492, which implies that transport by convection dominated microbial motility and chemotaxis.

These results suggested that the chemotactic bacteria carried along flow in the macropore (horizontal channel) sensed the concentration gradient from the NAPL attractant trapped in the low permeable region (porous network), and accumulated in the vicinity of the junctions between these two regions, which led to a build-up in bacterial population near the contaminant sources. Because the rate of biodegradation is proportional to the bacterial population density, we expect this accumulation of bacteria will enhance the biodegradation rate. However, as the groundwater velocities were increased from 0.5 to 5 m/d, the accumulation of chemotactic bacteria diminished from the NAPL sources. Model equations solved using COMSOL also supported the experimental findings about the microbial behaviors of *P. putida* strains in presence of toluene as chemoattractant.

#### 5.4.3 <u>No Flow in the H- $\mu$ Chip</u>

Bacteria were transported into the fine porous network under high convective velocities in the main channel, and the convective flow from the high permeable region adjacent to the porous structure carried bacteria into the narrow pore spaces in the low permeable region. This observation was also supported by the prediction from model equations within the COMSOL software routines, where the essential parameter for the porous structure permeability  $\kappa_{br}$  (1.0×10<sup>-9</sup> m<sup>2</sup>) was in the typical range of 10<sup>-8</sup> to 10<sup>-11</sup> m<sup>2</sup> for sand and gravel (Bear, 1988). Once bacteria occupied the entire porous network, the flow was stopped. Ten minutes after the flow was stopped, images of the bacterial distribution near toluene ganglia were recorded. Figures 5.9 and 5.10 show the bacterial distribution within pores at the edge of toluene ganglia under this condition. The cartoon in Figure 5.9a illustrates the expected bacterial distribution near one ganglion. Figure 5.9b shows a single image of the actual bacterial distribution and Figure 5.9c represents a composite of 30 images taken at different locations around the ganglion. The values of bacterial density in Figure 5.10 were normalized by the initial value in the main channel at injection. Accumulation of *P. putida* F1 increased as the distance from the toluene source decreased, while nonchemotactic bacteria were distributed evenly over the same distances and no accumulation was evident. This indicated that chemotactic bacteria responded to the concentration gradient of the attractant and migrated toward the regions where the toluene concentration was higher, and conversely, the nonchemotactic mutant did not present any observable response to the gradient profile. The bacterial density of chemotactic bacteria was approximately 15% greater at the visual edge of the toluene sources than at a distance of 500  $\mu$ m away from the sources.



**Figure 5.9** (a) Cartoon illustration and (b) image of chemotactic bacteria near a NAPL source. Each individual bright spot in (b) is a fluorescent bacterium dyed by FM 4-64, and (c) is a composite average from over 30 images of (b) at different locations around the toluene-water interface of a single ganglion.



Figure 5.10 The distribution of chemotactic and nonchemotactic bacteria near NAPL sources.

The differences in the distribution between the wild type and the mutant are statistically significant in the range of 0-300  $\mu$ m, with p < 0.0001 by the two-way ANOVA. The results of both chemotactic accumulation and statistical analysis are consistent with what were reported from previous studies in the single-pore device (Wang et al., 2012). However, the previous study only measured chemotaxis near one single pore slit; this study successfully captured similar results in a porous structure, designed to mimic a more complex groundwater system with contaminant sources.

The reason why the nonchemotactic bacteria results have bigger error bars than those of chemotactic ones is due to the difference between fluorescence intensities. DAPI was used to stain nonchemotactic bacteria, and its fluorescence intensity was lower than FM 4-64 and GFP, so its signal-to-noise ratio was also lower compared to the other fluorescence label, and that is why the error bars of nonchemotactic bacteria are bigger than the chemotactic ones.

Features of this microfluidic device resemble aspects of the agarose plug assay of Yu and Alam (1997). The plug assay has been widely used as a screening tool for bacterial chemotaxis (Parales et al., 2000; Parales and Harwood, 2002; Grimm and Harwood, 1999; Toepfer et al., 2012). One disadvantage of the assay is that properties of the agarose plug, which serves as the source of chemoattractant, limits the choices of chemicals that can be tested. NAPL chemicals are not very soluble in the aqueous agar solution. The reason why toluene is not recommended in plug assay is not only because of its low solubility in the agarose gel, but also because this organic chemical is highly volatile. When toluene is added to the hot melted agar solution during the process of making the central plug, an uncertain amount of toluene can evaporate quickly; thus, the toluene concentration in the agar is difficult to control. Furthermore, motile bacteria interact with and accumulate near the agar surface in a plug assay (Liu and Ford, 2009; Kusy and Ford, 2009), which may complicate analysis of the bacterial distribution from a mathematical model. The NAPL ganglia within the microfluidic system presented in this study provide an alternative approach, which addresses these issues.

#### 5.4.4 Bacterial Breakthrough Curves in the H-µChip

Figure 5.11 shows that a lower density of chemotactic bacteria was detected at the outlet at 0.25 m/d than the nonchemotactic mutant in H- $\mu$ Chip, as the normalized density of chemotactic bacteria dropped to about zero after 18 hours washout, and that of

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nonchemotactic mutant still remained at a value close to 0.1. This result indicated that more chemotactic bacteria remained in the microfluidic device than nonchemotactic bacteria at the slow flow rate. Because chemotactic P. putida F1 was stained with membrane dye FM 4-64, and the bacteria could immediately lose their motility once FM 4-64 was excited to show fluorescence (Appendix E), so direct observation on bacterial distribution was not allowed inside the porous network. Therefore, mathematical models were solved to support the statement above by determining the change in bacterial density remaining in the device on as a function of time. Numerical solution showed that the bacterial suspension in the horizontal channel was washed out quickly after one hour of buffer injection at 0.25 m/d, which could also be indicated by the plateau concentration of attractant at unit 1 for the first hour of injection, and the remaining bacterial population was within the porous network. Moreover, the average bacterial density in the porous network (not shown in the figure) was 60.7% of the inlet density for chemotactic bacteria after three hours of buffer wash at 0.25 m/d, and 53.6% for nonchemotactic bacteria under the same conditions. After 18 hours of wash out, the percentage of the remaining chemotactic bacteria dropped to 21.0%, and the value for nonchemotactic bacteria decreased to 15.4%. According to the model equations, chemotactic bacteria responded to the transverse gradient of attractant within the porous structure, and the induced chemotaxis effect redirected the bacterial population to migrate away from the macrochannel, thus, the bacteria remained in the "contaminant layer" for a longer time. All experimental data were also compared by two-way ANOVA tests, which show that there exists a significant difference between chemotactic and nonchemotactic groups at 0.25 m/d with p < 0.0001. The difference was not only shown by the experimental data,

but also predicted by the mathematical models solved using a finite element algorithm in COMSOL (Figure 5.11).



**Figure 5.11** The breakthrough curves of chemotactic and nonchemotactic bacteria at different flow rates. "chtx" and "nonch" in the legend stand for chemotactic and nonchemotactic bacteria respectively. The lines are the fitting results corresponding to different experimental datasets (dataset number n = 3). The fittings were run at a time interval of 20 min.

Another thing to notice is that the surface areas under the curves at 0.25 m/d are not the same. This difference in area is related to the washed-out bacterial population during the 18 hours, as  $B_{total} = B_{wash} (t) + B_{in} (t)$ , where B means the normalized bacterial population, and  $B_{total}$  is 100% and the same for both chemotactic and nonchemotactic bacteria.  $B_{wash}$  stands for the bacterial population that is washed out and is the surface area under the curve, and  $B_{in}$  is the bacterial population remained in the device. Both  $B_{wash}$  and  $B_{in}$  change with time (t), and  $B_{wash}$  increases with time because more and more bacteria are washed out. The area for chemotactic is smaller than that of nonchemotactic after 18 hours, and this means that less chemotactic bacteria are washed out, and thus indicates more chemotactic bacteria remain in the device due to chemotaxis effect in presence of attractant gradient. And because the flow rate is very slow (0.25 m/day), so the chemotactic bacteria in the device may be not able to be washed out at all. In addition, chemotactic bacteria were not totally washed out after 18 hours, and bacterial density did not drop to zero at the end of the curve; the value of the bacterial density at 18 hours was close to 0.01, which was hard to distinguish from zero in the figure, and neither did the fitting curve drop to zero.

If the flow rate increased to 5 m/d, both chemotactic and nonchemotactic bacteria were washed out very quickly, as both bacteria densities dropped to the level close to zero just after several minutes of injection, as shown in Figure 5.11. These breakthrough curves at high flow rate were significant different from the trends at low flow rate from a statistical viewpoint with p < 0.0001. However, at a flow rate of 5 m/d, the trend for chemotactic bacteria almost overlapped with that for nonchemotactic control, which means that the effect of chemotaxis was dominated by the large convection term. The dominance of high convective flow over chemotaxis effect was also found and supported by the results from Wang et al. (2012), in which high flow rates eliminated transverse bacterial accumulation due to chemotaxis. If we compare the bacterial swimming speed  $v_b$  (44 µm/s) with the flow rate, we notice that chemotaxis happens when  $v_b$  is larger than the flow rate (0.25 m/d = 2.9 µm/s), and the phenomenon diminishes when  $v_b$  is smaller than the flow rate (5 m/d = 58 µm/s), which is consistent with the previous study of *P*.

*putida* bacteria and toluene in the single-pore device (Wang et al., 2012). Because the microfluidic device mimics the essential features (pore sizes, contaminant profile and heterogeneity etc.) of in-situ NAPL contaminated sites, it may provide a good indication of how bacterial chemotaxis will influence bacterial distributions in natural aquifers, and also provide evidence that chemotactic bacteria accumulate near contaminant sources in the low permeable region under certain groundwater flow rates. The breakthrough curve for chemotaxis differentiates from the one for nonchemotaxis, when groundwater flow rates are generally slow (0.1 - 1 m/d), but the difference diminishes at a higher flow rate. This information can guide us to build up correct strategies to apply chemotaxis in fieldscale studies. According to this information, chemotaxis can be tested and possibly accelerate bioremediation in the contaminated sandy aquifer at Cape Cod, MA, as the sites have similar porous structure and groundwater velocity from 0.25 to 0.33 m/d (Harvey and Garabedian, 1991); however, chemotaxis would not make a difference if the flow rates are much higher than that. The experimental results for 5 m/d were also supported by the fitted curves in Figure 5.11, as both chemotactic and nonchemotactic bacteria subjected to a quick washout under bulk flow at 5 m/d. However, the fitting did not match well with the data points at two hours of injection; the experimental observation showed a higher density of both bacterial strains than the fitted results at either flow rate. From the aspect of experiment, time zero of the injection was set to be the time when the injectate changed from bacterial suspension to washout buffer at the inlet, so the injectate change might generate the delay of washout due to various of reasons about the device and the operation. From the aspect of fitting, different values of permeability  $\kappa_{br}$  could affect the breakthrough trends to some extent at the slow flow rate, and an accurate estimation of this value needed to be developed in future, in order to obtain more accurate fittings. Currently,  $\kappa_{br}$  is the only fitting parameter, while all other parameters are either calculated in this study or reported by literatures.

#### 5.5 Implications

The chemotaxis effect is proved to efficiently deliver more degrading bacteria to the NAPL contaminant sources in low permeable region, based on the data from the continuous injection, no flow and buffer wash experiments in this chapter. The results are also supported by mathematical models and statistical analysis. There is no direct observation of biodegradation, but because many NAPL contaminants such as toluene are degradable by P. putida F1, the experimental observations of biased accumulation of chemotactic bacteria around the NAPL sources within the low permeable region will lead to an increase of contaminant consumption, and because toluene is also one of the carbon sources for *P. putida* strains, a faster growth of overall bacterial population is expect to happen, which will further accelerate the biodegradation to a greater extent. Therefore, bacterial chemotaxis reveals a large potential to improve the efficiency of bioremediation. However, groundwater flow rate is an important factor to consider before applying chemotactic bacteria to contaminated sites. In general, a local flow rate smaller than bacterial swimming speed may allow sufficient retention time for chemotactic bacteria to swim toward the contaminant sources in the transverse direction; however, a higher flow rate overwhelms the chemotaxis effect and carries bacteria away along the groundwater flow pathway.

# CHAPTER 6

# **SUMMARY AND**

# **C**CONCLUSIONS

### 6.1 Summary

Two different microfluidic devices were designed and fabricated to study bacterial chemotaxis. Convection free microfluidic device (CF- $\mu$ Chip) successfully extremely simplified the experimental condition to measure the two essential chemotaxis parameters: chemotactic sensitivity coefficient  $\chi_0$  and chemotactic receptor constant  $K_c$ . CF- $\mu$ Chip provided an accurate method to measure these parameters, and decoupled the compensating effect between  $\chi_0$  and  $K_c$ , which was important to solve but neglected in previous studies, by testing bacterial response to a different attractant concentration. The device material was changed from glass to an air permeable polymer (PDMS), which could keep the oxygen level in the device so that aerobic bacteria remained motile and also allowed a simple and reversible assembly of the device. Both *Pseudomonas putida* and *Escherichia coli* strains were studied with corresponding attractant and labeled with different fluorescence dyes, and the bacterial densities were recorded as fluorescence light intensities from microscope linked camera. More chemotactic population migrated into the channel at appropriate attractant concentration than nonchemotactic bacteria, and the predicted chemotaxis parameters were consistent with the published results and the values calculated from related work.

The other microfluidic device (H-µChip) was designed to mimic the heterogeneous groundwater system that was exposed to NAPL contaminant sources. The degrading bacteria were injected in the high permeable region with convective flow within the typical range of groundwater flow rates, and the NAPL contaminants were trapped at designated locations in the low permeable region. *Pseudomonas putida* F1 and toluene were used as the test models for chemotactic bacteria and attractant. Bacterial distributions were compared between the wild type and the nonchemotactic mutant in three different experimental conditions: intersection between horizontal channel and porous network with continuous injection of bacteria, adjacent area outside each toluene ganglion with no flow, and the device outlet with continuous buffer wash. Evidences of chemotaxis were found for all different conditions by comparing its effect with nonchemotactic bacterial distribution. The impact of flow rate on chemotaxis was also studied in the two with-flow conditions.

Mathematical models were solved numerically in a finite element solver COMSOL and the fitted results supported the experimental findings throughout this study. Statistical analysis was also widely applied to the quantitative comparisons of experiments.

#### 6.2 Conclusions

Fluorescence labeling was successfully used to detect bacteria. The current fluorescence method created a sufficient signal-to-noise ratio so that the fluorescence intensity could directly indicate the bacterial density, and this method is more accurate and takes much less time to analyze than the conventional methods, such as counting bacteria either under the microscope or on the computer screen. Furthermore, chemotactic and nonchemotactic bacteria were mixed and injected together into the devices, and this reduced many possible operational and systematic errors from experiment to experiment.

The material of CF- $\mu$ Chip was changed from glass to PDMS, and the latter ensured sufficient oxygen accessibility to keep aerobic bacteria staying healthy and motile in the device.

The fitting results from CF- $\mu$ Chip indicated that the averaged value of chemotactic sensitivity coefficient  $\chi_0$  is  $1.8 \times 10^{-4}$  cm<sup>2</sup>/s, and chemotactic receptor constant  $K_c$  is 1 mM for *P. putida* F1 to toluene, which are similar to the reported values for *P. putida* F1/TCE (Olson et al., 2004). Modeling fitting to experimental data of *E. coli* HCB1 with  $\alpha$ -methylaspartate ( $\alpha$ -mASP) showed that  $\chi_0$  is  $2.4 \times 10^{-4}$  cm<sup>2</sup>/s and  $K_c$  is 0.13 mM, both supported by previous reference (Lewus and Ford, 2001). When groundwater flow rate was small in H-µChip, chemotactic bacteria formed a biased transverse accumulation toward the NAPL contaminant sources in the low permeable porous network; however, such biased movement did not occur for nonchemotactic bacteria. Thus, chemotactic bacteria showed the ability to direct more cellular population into the contaminated region with fine pore sizes.

At the slow groundwater flow rate in H- $\mu$ Chip, chemotactic bacteria was more difficult to be washed out from the device, because the chemotaxis effect induced by the attractant gradient in the porous network generated a transverse migration of bacteria to confront the major bulk flow in the horizontal channel. This longer retention time of chemotactic bacteria in the contaminated porous network increased the opportunity of contaminant consumption.

More direct evidence of chemotaxis was found in vicinity of toluene ganglia in H- $\mu$ Chip when the flow stopped. Chemotactic bacteria exhibited a 15% more accumulation near one contaminant source than the ones located 500  $\mu$ m away from the ganglion, while nonchemotactic bacteria followed an even distribution. The increase level and the location of accumulation were consistent with previous results about chemotactic accumulation near a toluene/water interface within a single pore interstice (Wang et al., 2012).

Flow rate played a major role in affecting chemotaxis effect in porous media. A rough estimation showed that if the flow rate was smaller than the bacterial swimming speed, then it left sufficient time for bacteria to interact with the attractant gradient on the transverse direction and redirect their movement, but if the flow rate was higher, the retention time for bacteria to interact with chemical change in the surrounding was fairly small, majority of the bacterial population would be carried away by the dominate convective flow along the water pathway.

Numerical solutions solved from the mathematical models also matched the experimental results in this study, and the fitting parameters are listed in Table 6.1.  $\chi_0$  and  $K_c$  were calculated based on the experimental data from CF-µChip.

	P. putida F1 and F1 CheA	<i>E. coli</i> HCB1 and HCB437
<i>T</i> [K]	298	298
$\chi_0  [\times 10^{-8}  m^2/s]$	1.8	2.4
$K_c$ [mM]	1.0	0.125
$b_0  [\mathrm{mol/m^3}]$	1.0	1.0
<i>v<sub>b</sub></i> [µm/s]	44	22.8
$D_a [\times 10^{-10} \text{ m}^2/\text{s}]$	9.5 (toluene)	8.7 (α-mASP)
$\mu_0  [\times 10^{-10}  \mathrm{m^2/s}]$	13	2.4 and 17
$\kappa_{br} [\times 10^{-9} \text{ m}^2]$	1.0	N/A
$\epsilon_p$	0.43	N/A

Table 6.1 Main parameters for the computational fitting of bacterial chemotaxis

#### 6.3 **Recommendations**

 $CF-\mu Chip$  is an accurate and convenient tool to measure chemotaxis parameters, and should be widely used for different bacteria and chemical stimulus combinations, in order to enrich the poorly quantitative database for bacterial chemotaxis. Multiple attractants/repellents can also be added into the channel at the same time to study chemotaxis in a more complex chemical environment. However, in order to capture more accurate values of chemotaxis parameters, sensitivity of fluorescence detection needs to be enhanced and background noise, such as unstable light source from arc lamp, needs to be reduced. Bacterial distribution in presence of a wider range of attractant concentration is recommended to test in order to find out if  $K_{c,low}$  exists for certain bacterial strains. Furthermore, NAPL biodegradation should be studied in the H-µChip, and the biodegradation process can be recorded either as the decrease in NAPL concentration at the outlet or the increase of bacterial population in the device on a time scale.

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## **APPENDIX A: COMSOL SETTINGS**

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C Initial Values 1 E	u [Velocity field (fp/fp1) •	-0.001		$\bigcirc$		$\bigcirc$		$\bigcirc$		$\bigcirc$		
Outflow 1	✓ Coordinate System Selection	0.002										
Concentration 1 Mobile Fluid, Immobile Solid 2	Coordinate system:	0.002			$\frown$		$\frown$		$\frown$			
Species Transport in Porous Media 2 (chp	Global coordinate system	-0.003			$\bigcirc$		$\bigcirc$		$\bigcirc$			1
No Flux 1 Initial Values 1	✓ Porous Medium Porosity:	-0.004										
Outflow 1	€ 1 l	_		$\frown$		$\cap$		$\bigcirc$		$\bigcirc$		
Mobile Fluid, Immobile Solid 2	Bulk density:	-0.005										
Study 1	Pb 1000[kg/m^3] kg/m <sup>3</sup>			~		~		~		~		
Step 1: Stationary Step 2: Time Dependent	Adsorption	-0.006			$\sim$		$\sim$					
Solver Configurations	Dispersion	-0.007			( )		( )		( )			
Solver 1	▼ Diffusion				$\bigcirc$		$\smile$		$\bigcirc$			
xxw Dependent Variables 1	$D_{n,i} = e \tau_{F,i} D_{F,i}$	-0.008										
Stationary Solver 1	Fluid phase material:	_										
Compile Equations: Time Depende	Water (mat1)	-0.009										
New Dependent Variables 2	Fluid phase diffusion coefficient:	0.07										
Study 2	DF.a User defined	-0.01										
Results	Da m <sup>2</sup> /s	.0.011										
Solution 1	Fluid phase tortuosity factor:								1 10 000			
Cut Line 2D 1	Millington and Quirk model		°-0.002 0	'0.	002 '0.	004 '0.	006 '0.0	08 '0.01	0.012	0.014	0.016 0	.018
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Figure A.4 General settings for the solvers of the modules in COMSOL.

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a Free and Porous Media Flow (fp)		0.007									
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Initial Values 1		0.002									
Inlet1	Override and Contribution										
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Outflow1	▼ Coordinate System Selection										
Concentration 1	Confederation .	-0.002									
Mobile Fluid, Immobile Solid 2	Coordinate system:										
a 🐹 Species Transport in Porous Media 2 (chp	Global coordinate system	-0.003		( )							ŀ
Mobile Fluid, Immobile Solid 1	* Porous Medium					$\sim$		$\bigcirc$			
No Flux 1	-	0.007									
Inflow 1	Porosity:	-0.004	100000								
Outflow 1	e epsilon 1										
Mobile Fluid, Immobile Solid 2	Bulk density:	-0.005									
G Mesh 1	Pb 1000[ka/m^3] ka/m <sup>3</sup>								$\sim$		
a 💥 Study 1		-0.006									
Step 1: Stationary	<ul> <li>Adsorption</li> </ul>										
Solver Configurations	Dispersion	-0.007									
a 🙀 Solver1	- Diffusion										
💱 Compile Equations: Stationary		-0.008									
New Dependent Variables 1	$D_{q,i} = eT_{F,i}D_{F,i}$	-0.008									
Stationary Solver 1	Fluid phase material:	_		(							
Compile Equations: Time Depend	Water (mat1)	-0.009									
Dependent Variables 2	Fluid phase diffusion coefficient:										
b Ko Time-Dependent Solver 1	De Duranteret al	-0.01									
Study 2	-ra per denes										
a 💽 Results	De m²/s	-0.011									
Solution 1	Fluid phase tortuosity factor:			la sea '	In one i	1		1		la su s '	
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Figure A.5 General settings for the solvers of the modules in COMSOL.

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Larry Toluene Trap Porous Time Lapse Correct.rr      A     B Global Definitions     P Parameters	Domain Selection Selection All domains	0.005							_ · _ · _ ·	Munip
Model 1 (mod1)	1 2 (overridden)	0.004								
PA Geometry 1     Second Porous Media Flow (fp)	3 (not applicable) 4 (not applicable) 5 (not applicable)	0.003								
Fluid Properties 1     Wall 1     Ditial Values 1	b (not applicable) 7 (not applicable) 8 (not applicable) *	0.002								
Inlet 1 Outlet 1	Override and Contribution									
Porous Matrix Properties 1     Porous Matrix Properties 2	Equation     Model Inserts	0.001								
▲ A Species Transport in Porous Media (chpm <sup>D</sup> Mobile Fluid, Immobile Solid 1	Velocity field:	ō			$\sim$		$\sim$		$\sim$	
No Flux 1 Initial Values 1	u User defined 🔹	-0.001		)						
<ul> <li>Inflow 1</li> <li>Outflow 1</li> <li>Concentration 1</li> </ul>	1*u+(2*vb/3)*tanh(Chi*Kd*ev/(2*vb*(Kd+e)*2))*0 x 1*v+(2*vb/3)*tanh(Chi*Kd*ey/(2*vb*(Kd+e)*2))*0 y	-0.002					-		-	
Mobile Fluid, Immobile Solid 2     Mobile Transport in Porous Media 2 (chp     Mobile Fluid, Immobile Solid 1	Coordinate System Selection     Coordinate system:	F -0.003		$\bigcirc$		$\bigcirc$		$\bigcirc$		
So Flux 1 Control Values 1	Global coordinate system 💌	-0.004								
<ul> <li>Inflow 1</li> <li>Outflow 1</li> </ul>	Porous Medium     Porosity:	-0.005	(	)	$\cap$		$\bigcirc$		$\cap$	
Mobile Hurd, Immobile Solid 2  Mesh 1  Solid 1	e 1 1			/	$\bigcirc$		$\bigcirc$		$\bigcirc$	
C Step 1: Stationary	Bulk density: Pb 1000[kg/m^3] kg/m <sup>3</sup>	-0.006		_		$\sim$		$\sim$		
Solver Configurations     Solver 1	Adsorption	-0.007								
Compile Equations: Stationary	Dispersion	-0.008		~		$\sim$		~		
Stationary Solver 1 Store Solution 3	▼ Diffusion $D_{a,i} = e\tau_{F,D_{F,i}}$	-0.009								
Compile Equations: Time Depende Dependent Variables 2	Fluid phase material:									
Study 2 Time-Dependent Solver 1	Water (mat)	-0.01								
Results     Data Sets	DF.b User defined	-0.011								
Cut Line 2D 1	Db m²/s		-0.002 0	0.002	0.004 0.0	0.0	08 0.01	0.01	2 0.014	0.016
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Figure A.6 General settings for the solvers of the modules in COMSOL.



Figure A.7 General settings for the solvers of the modules in COMSOL.

### **APPENDIX B: TWO-WAY ANOVA ANALYSIS IN CF-µCHIP**

**Table B.1** Statistical comparison between the distributions of *P. putida* F1 at 2 mM

toluene and 0.2 mM toluene in the CF- $\mu$ Chip, as illustrated in Figure 4.6.

Table Analyzed	Data 1			
Two-way ANOVA				
Source of Variation	% of total variation	P value		
Interaction	1.38	< 0.0001		
Column factor	2.27	< 0.0001		
Row factor	94.81	< 0.0001		
Source of Variation	P value summary	Significant?		
Interaction	***	Yes		
Column factor	***	Yes		
Row factor	***	Yes		
Source of Variation	Df	Sum-of-squares	Mean square	F
Interaction	22	1843	83.79	3.733
Column factor	1	3039	3039	135.4
Row factor	22	126900	5769	257.1
Residual	92	2065	22.44	
Number of missing values	0			

Data analyzed: Data 1

Source of Variation	Degrees of Freedom	Sum of Squares	
	Mean square		
Column factor	1.0	3039	3039
Row factor	22.0	126900	5769
Interaction	22.0	1843	
	83.79		
Residual (error)	92.0	2065	
	22.44		
Total	137.0	133900	

**Table B.2** Statistical comparison between the distributions of *P. putida* F1 at 2 mM toluene and nonchemotactic *P. putida* F1 CheA in the CF-μChip, as illustrated in Figure 4.6.

Data 1

Table Analyzed

Row factor

Interaction

Total

Residual (error)

Two-way ANOVA				
Source of Variation	% of total variation	D valua		
Jource of Variation		< 0.0001		
Column factor	5.04 7 47	< 0.0001		
Row factor	88.50	< 0.0001		
Source of Variation	P value summary	Significant?		
Interaction	***	Yes		
Column factor	***	Yes		
Row factor	***	Yes		
Source of Variation	Df	Sum-of-squares	Mean square	F
Interaction	15	0.3204	0.02136	13.14
Column factor	1	0.7872	0.7872	484.3
Row factor	15	9.328	0.6218	382.6
Residual	64	0.1040	0.001625	
Number of missing values	0			
Data analyzed: Data	ta 1			
Source of Variation	<u>n Deg</u> Mea	rees of Freedom n square	Sum of Squares	
Column factor	1.0 0.78	72	0.7872	

15.0 0.6218 15.0

64.0

95.0

0.02136

0.001625

9.328

0.3204

0.1040

10.54

**Table B.3** Statistical comparison between the distributions of *P. putida* F1 at 0.2 mM

toluene and nonchemotactic P. putida F1 CheA in the CF-µChip, as illustrated in Figure

4.6.

Table Analyzed	Data 1

### Two-way ANOVA

Source of Variation Interaction Column factor Row factor	% of total variation 0.86 1.85 96.29	P value 0.0002 < 0.0001 < 0.0001		
Source of Variation	P value summary	Significant?		
Interaction	***	Yes		
Column factor	***	Yes		
Row factor	***	Yes		
Source of Variation	Df	Sum-of-squares	Mean square	F
Interaction	15	0.08488	0.005659	3.631
Column factor	1	0.1829	0.1829	117.4
Row factor	15	9.533	0.6356	407.8
Residual	64	0.09975	0.001559	
Number of missing values	0			

Data analyzed: Data 1

Degrees of Freedom	Sum of Squares
Mean square	
1.0	0.1829
0.1829	
15.0	9.533
0.6356	
15.0	0.08488
0.005659	
64.0	0.09975
0.001559	
95.0	9.901
	Degrees of Freedom <u>Mean square</u> 1.0 0.1829 15.0 0.6356 15.0 0.005659 64.0 0.001559 95.0
**Table B.4** Statistical comparison between the distributions of *E. coli* HCB1 at 3 mM  $\alpha$ methylaspartate and 0.3 mM  $\alpha$ -methylaspartate in the CF- $\mu$ Chip, as illustrated in Figure

Table Analyzed	Data 1			
Two-way ANOVA				
Source of Variation	% of total variation	P value		
Interaction	5.69	< 0.0001		
Column factor	6.19	< 0.0001		
Row factor	86.45	< 0.0001		
Source of Variation	P value summary	Significant?		
Interaction	***	Yes		
Column factor	***	Yes		
Row factor	***	Yes		
Source of Variation	Df	Sum-of-squares	Mean square	F
Interaction	16	0.5756	0.03598	14.43
Column factor	1	0.6263	0.6263	251.2
Row factor	16	8.749	0.5468	219.4
Residual	68	0.1695	0.002493	
Number of missing values	0			
4.8.				

Data anal	yzed:	Data	1
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Source of Variation	Degrees of Freedom	Sum of Squares
	Mean square	
Column factor	1.0	0.6263
	0.6263	
Row factor	16.0	8.749
	0.5468	
Interaction	16.0	0.5756
	0.03598	
Residual (error)	68.0	0.1695
	0.002493	
Total	101.0	10.12

**Table B.5** Statistical comparison between the distributions of *E. coli* HCB1 at 3 mM  $\alpha$ methylaspartate and nonchemotactic *E. coli* HCB437 in the CF- $\mu$ Chip, as illustrated in Figure 4.8.

Table Analyzed	Data 1			
Two-way ANOVA				
Source of Variation	% of total variation	P value		
Interaction	3.22	< 0.0001		
Column factor	7.15	< 0.0001		
Row factor	88.33	< 0.0001		
Source of Variation	P value summary	Significant?		
Interaction	***	Yes		
Column factor	***	Yes		
Row factor	***	Yes		
Source of Variation	Df	Sum-of-squares	Mean square	F
Interaction	16	0.3659	0.02287	10.57
Column factor	1	0.8125	0.8125	375.6
Row factor	16	10.03	0.6270	289.9
Residual	68	0.1471	0.002163	
Number of missing values	0			
Data analyzed: Data 1				
Source of Variation	<u>Degrees of Free</u> Mean square	edom Sum of S	Squares	
Column factor	1.0 0.8125	0.8125		
Row factor	16.0 0.6270	10.03		
Interaction	16.0 0.02287	0.3659		
Residual (error)	68.0 0.002163	0.1471		
Total	101.0	11.36		

**Table B.6** Statistical comparison between the distributions of *E. coli* HCB1 at 0.3 mM  $\alpha$ methylaspartate and nonchemotactic *E. coli* HCB437 in the CF- $\mu$ Chip, as illustrated in Figure 4.8.

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Table Analyzed	Data 1			
Two-way ANOVA				
Source of Variation	% of total variation	P value		
Interaction	9.62	< 0.0001		
Column factor	25.08	< 0.0001		
Row factor	64.34	< 0.0001		
Source of Variation	P value summary	Significant?		
Interaction	***	Yes		
Column factor	***	Yes		
Row factor	***	Yes		
Source of Variation	Df	Sum-of-squares	Mean square	F
Interaction	16	1.099	0.06867	42.40
Column factor	1	2.865	2.865	1769
Row factor	16	7.351	0.4594	283.7
Residual	68	0.1101	0.001620	
Number of missing values	0			
Data analyzed: Data 1				
Source of Variation	Degrees of Free Mean square	edom Sum of S	Squares	
Column factor	1.0 2.865	2.865		
Row factor	16.0 0.4594	7.351		
Interaction	16.0 0.06867	1.099		
Residual (error)	68.0 0.001620	0.1101		

101.0

11.42

Total

## **APPENDIX C: TWO-WAY ANOVA ANALYSIS IN H-µCHIP**

Table C.1 Statistical comparison between the distributions of *P. putida* F1 and

nonchemotactic P. putida F1 CheA at the junctions in the H-µChip at 0.5 m/d, as

illustrated in Figure 5.6.

Table Analyzed	Data 1			
Two-way ANOVA				
Source of Variation	% of total variation	P value		
Interaction	2.96	0.9196		
Column factor	66.33	< 0.0001		
Row factor	3.22	0.9019		
Source of Variation	P value summary	Significant?		
Interaction	ns	No		
Column factor	***	Yes		
Row factor	ns	No		
Source of Variation	DfSu	m-of-squares I	Mean square	F
Interaction	7	0.003568	0.0005097	0.3538
Column factor	1	0.07996	0.07996	55.50
Row factor	7	0.003878	0.0005539	0.3845
Residual	23	0.03314	0.001441	
Number of missing values	6			
Data analyzed: Data 1				
Source of Variation	Degrees of Free Mean square	edom <u>Sum</u>	of Squares	
Column factor	1000000000000000000000000000000000000	0.079	996	
Row factor	0.07996 7.0	0.00	3878	
	0.0005539			
Interaction	7.0	0.003	3568	
	0.0005097			
Residual (error)	23.0	0.033	314	
	0.001441			
Total	38.0			

**Table C.2** Statistical comparison between the distributions of *P. putida* F1 at the

junctions in the H- $\mu$ Chip at both 0.5 m/d and 5 m/d, as illustrated in Figure 5.7.

Table Analyzed	Data 1			
Two-way ANOVA				
Source of Variation	% of total variation	P valu	le	
Interaction	7.84	0.191	8	
Column factor	63.55	< 0.000	1	
Row factor	5.25	0.431	8	
Source of Variation	P value summary	Significant	t?	
Interaction	ns	Ν	0	
Column factor	***	Ye	es	
Row factor	ns	Ν	0	
Source of Variation	DfSu	um-of-square	es Mean square	F
Interaction	7	0.00600	7 0.0008582	1.533
Column factor	1	0.0487	0.04872	87.02
Row factor	7	0.00402	5 0.0005749	1.027
Residual	32	0.0179	0.0005598	
Number of missing values	0			
Data analyzed: Data 1				
Source of Variation	Degrees of Free Mean square	edom <u>Su</u>	m of Squares	
Column factor	1.0 0.04872	0.0	04872	
Row factor	7.0 0.0005749	0.0	004025	
Interaction	7.0 0.0008582	0.0	006007	
Residual (error)	32.0 0.0005598	0.0	01791	
Total	47.0	0.0	07666	

**Table C.3** Statistical comparison between the breakthrough curves of *P. putida* F1 and nonchemotactic CheA at the outlet in the H- $\mu$ Chip at 0.25 m/d, as illustrated in Figure

5.10.

Table Analyzed	Data 1				
Two-way ANOVA					
Source of Variation Interaction	% of total variation 0.71	P va 0.3	alue 853		
Column factor Row factor	3.61 92.82	< 0.0 < 0.0	001 001		
Source of Variation Interaction Column factor Row factor	P value summary ns *** ***	Significa	ant? No Yes Yes		
Source of Variation	DfS	um-of-squ	ares M	lean square	F
Interaction Column factor Row factor Residual	9 1 9 40	0.04 0.2 6. 0.1	684 390 146 894	$\begin{array}{c} 0.005205\\ 0.2390\\ 0.6828\\ 0.004735\end{array}$	1.099 50.48 144.2
Number of missing values	0				
Data analyzed: Data 1					
Source of Variation	Degrees of Free Mean square	eedom	Sum o	of Squares	
Column factor	$\overline{1.0}$ 0.2390		0.239	0	
Row factor	9.0 0.6828		6.146		
Interaction	9.0 0.005205		0.046	84	
Residual (error)	40.0 0.004735		0.189	4	

59.0

6.621

Total

Table C.4 Statistical comp	arison between the bre	akthrough	curve	es of <i>P. putida</i>	F1 and
nonchemotactic CheA at th	e outlet in the H-µChij	o at 5 m/d	, as ill	ustrated in Fig	ure 5.10.
Table Analyzed	Data 1				
Two-way ANOVA					
Source of Variation	% of total variation	Рv	value		
Interaction	0.33	0.′	7194		
Column factor	0.02	0.:	5080		
Row factor	97.49	< 0.0	0001		
Source of Variation	P value summary	Signific	cant?		
Interaction	ns		No		
Column factor	ns		No		
Row factor	***		Yes		
Source of Variation	DfS	um-of-squ	uares N	lean square	F
Interaction	9	0.0	1752	0.001947	0.6832
Column factor	1	0.00	1271	0.001271	0.4462
Row factor	9	5	.160	0.5733	201.2
Residual	40	0.	1140	0.002849	
Number of missing values	0				
Data analyzed: Data 1					
Source of Variation	Degrees of Fr	eedom	Sum	of Squares	
Column factor	1.0 0.001271		0.001	271	
Row factor	9.0		5.160	)	
Interaction	0.5/33		0.017	'52	
	0.001947		0.01/		
Residual (error)	40.0		0.114	0	
	0.002849				
Total	59.0		5.292		

**Table C.5** Statistical comparison between the breakthrough curves of *P. putida* F1 at the outlet in the H- $\mu$ Chip at both 0.25 and 5 m/d, as illustrated in Figure 5.10.

Table Analyzed	Data 1			
Two-way ANOVA				
Source of Variation	% of total variation	P value		
Interaction	6.22	< 0.0001		
Column factor	3.95	< 0.0001		
Row factor	87.57	< 0.0001		
Source of Variation	P value summary	Significant?		
Interaction	***	Yes		
Column factor	***	Yes		
Row factor	***	Yes		
Source of Variation	DfSun	n-of-squares N	lean square	F
Interaction	9	0.3818	0.04243	12.22
Column factor	1	0.2427	0.2427	69.90
Row factor	9	5.378	0.5976	172.1
Residual	40	0.1389	0.003472	
Number of missing values	0			
Data analyzed: Data 1				
Source of Variation	Degrees of Free Mean square	dom <u>Sum</u>	of Squares	
Column factor	1.0 0.2427	0.242	7	
Row factor	9.0 0.5976	5.378		
Interaction	9.0 0.04243	0.381	8	
Residual (error)	40.0 0.003472	0.138	9	
Total	59.0	6.142		

# APPENDIX D: CORRELATION BETWEEN OPTICAL DENSITY AND LIGHT INTENSITY IN THE μCHIP

One conventional way to determine bacterial concentration is to count individual cells, which is time-consuming and error-prone. Instead, for this analysis, it was assumed that the gray level intensity of each cell was similar to each other in the population, thus allowing the light intensity to be correlated with the bacterial concentration in terms of optical density.

The background light intensity decreased the contrast of the bacteria, so the filters provided with Image J software were used to remove the background. Image of bacterial distribution without the background is presented as Figure D.1 (a). The white dots in the image are the bacterial cell bodies. Because the bacteria were discrete points, 150 images were taken at the same experimental condition, and then averaged using Image J to yield a single image as shown in Figure D.1 (b). This process reduced the statistical variation in the calibration between bacterial concentration and light intensity.



**Figure D.1** (a) Background removed by Image J. The white spots are the bacteria. (b) The image averaged from 150 images similar to (a) under the same experimental condition.

Five different concentrations of the bacterial suspension were prepared. The optical density of the bacterial suspension was measured directly by a spectrometer, and the bacterial light intensity inside the microfluidic device was obtained from the ROI in Figure D.2, when there was no attractant. The correlation between the optical density and the light intensity is shown in Figure D.3.



**Figure D.2** The ROI is the square formed by the dashed line, and the integrated intensity in the ROI was obtained by Image J for five different bacterial concentrations.



Figure D.3 Correlation between the optical density (OD) and the light intensity of bacterial concentration in the microfluidic device.

The bacterial concentration and the light intensity from the image had a strongly positive correlation. Therefore, the light intensity could be used to represent the bacterial concentration. However, in Figure D.2 the value of light intensity at OD=0 was larger than zero, which meant that there was still some background noise from the image after the first background removal; thus, a second background removal was implemented in the following data analysis.

## APPENDIX E: VALIDATION OF BACTERIA/ATTRACTANT SYSTEM, IMAGE ANALYSIS AND EXPERIMENTAL SETUP

#### E.1 Introduction

The main purpose of this chapter is to document the results from the preliminary tests for the bacteria/attractant pairs used in this study, the methodology for data analysis and the flow study in the microfluidic devices.

Section E.2 reviews the quality of the various fluorescence staining used for bacteria. Section E.3 presents the correlation between fluorescence intensity and bacterial density and between optical density and bacterial density, which validates the methodology for image analysis. Section E.4 summarizes the impact of the membrane dye FM 4-64 on bacterial motility and suggests the correct way to use the molecular probe in this study. Section E.5 introduces the collaborative work on the generic transformation of GFP into *P. putida* strains and related problems. Section E.6 provides the simulation results about the flow patterns in microfluidic devices (µChip).

### **E.2** Bacterial Fluorescence

The quality of bacterial fluorescence was checked using the microscopic setup mentioned in Section 3.6. The images from both fluorescent view and bright field view are shown in Figure E.1. All fluorescence labeled cells produced a strong signal that was easily distinguished from the background. The calibration between the bacterial fluorescence and bacterial density is given in Figure E.2 in section E.2.



**Figure E.1** (a) *P. putida* F1 stained with FM 4-64, (b) *P. putida* F1 CheA stained with DAPI, (c) *E. coli* HCB1 tagged with GFP and (d) *E. coli* HCB437 stained with DAPI under 20× objective.

## E.3 Optical Density vs. Bacterial Density vs. Fluorescence

As mentioned in Chapter 3, the correlation was determined by using GFP tagged *E*. *coli* bacteria. The correlation between the  $OD_{590}$  and bacterial density is shown in Figure E.2a with a R<sup>2</sup> equaling to 0.99, and the correlation between normalized GFP intensity and bacterial density (Figure E.2b) also have a very high correlation coefficient (R<sup>2</sup> = 0.99), and these results mean that both OD value and GFP fluorescence can represent the actual bacterial density in the working range. With the confidence from the results about GFP fluorescence, it is reasonable to deduce that the FM 4-64 and DAPI stains should also be representative of bacterial density.





**Figure E.2** Correlations between (a)  $OD_{590}$  and bacterial density and between (b) normalized GFP intensity and bacterial density. The triangle and diamond points are the experimental data, and the straight lines are the corresponding fitting curves.

## E.4 FM 4-64 Impact on Bacterial Motility

The dye FM 4-64 itself did not affect the motility. Stained and unstained *E. coli* HCB1 with GFP from same batch were mixed and injected into one inlet of the CF- $\mu$ Chip, and 10% RMB buffer was injected into the other inlet. Images of bacterial distribution in the cross channel was taken for both GFP and FM 4-64 fluorescence at 0 and 25 minutes of injection, and images at time 0 was chosen as the background noise and subtracted from images at time 25 minutes, and then the results of the processed

images were plotted in Fig. E.3. The two groups of bacteria followed the same trend and could not differentiate from each other based on the statistical analysis (two-way ANOVA), and the experimental data also matched the simulation result using reported value of bacterial random motility. Both the stained and unstained bacteria had the similar motility and the dye itself did not affect the bacterial motility. The unstained bacteria had a lower population density than the stained ones from 1 to 1.5 mm, and that was induced by experimental errors. Some GFP fluorescence might inadvertently be subtracted when removing the background noise, because the signal-to-noise ratio of GFP was lower than FM 4-64. This difference from 1 to 1.5 mm was also not significant according to statistical analysis.

The experimental data were then fitted using Eqn 4.4, and the best fitting were determined using the method of least squares, and the values of bacterial random motility were reported accordingly as following. Then the uncertainty of bacterial random motility was determined by allowing a 10% increase in the value of the least squares, then the fitting gave us the random motility =  $1.1 \pm 0.2 \times 10^{-10}$  m<sup>2</sup>/s for the FM 4-64 stained bacteria and  $0.7 \pm 0.2 \times 10^{-10}$  m<sup>2</sup>/s for the unstained bacteria. The student t-test showed that there was no significant difference between the two values, so that meant that FM 4-64 had no impact on bacterial motility.



**Figure E.3** Normalized fluorescence intensities from GFP (blank diamond) and FM 4-64 (black square) in the cross channel at 25 minutes of injection. The solid curve represents the fitting result for the FM 4-64 stained bacteria, and the dash line for the unstained bacteria (only tagged with GFP).

An interesting result about FM 4-64 staining was that although the membrane dye itself did not hurt the bacterial properties, the excitation of fluorescence might damage the bacterial motility. The reason was probably because the FM 4-64 dye was linked to the plasmatic membrane, and the fluorescence excitation generated extremely high level of energy absorbance and energy release in a very short time, which could easily lead to malfunctions of the cell membrane. Although no evidence indicated that the high-energy release might kill the cell, the bacterial flagella could be greatly impacted as they located peritrichously on the cell membrane. This suggested that the bacterial fluorescence from FM 4-64 could not be checked in real time in CF- $\mu$ Chip, as the bacterial distribution was purely established by their motility, and there was also no renewal in the bacterial population; the fluorescence should be checked at the end of the experiments for this microfluidic device. For H-µChip, the fluorescent intensity still could be recorded in real time at the outlet of microfluidic device, so that the excitation would not affect the functioning bacteria in the main channels. The dimension of the affected zone was determined by the arc lamp precision and specific objective, and it could be directly measured from the bright area covered by the focused light beam. As shown in Figure E.4, the affected zone (the green circle) has a diameter of about 2-3 mm, and it is far away from the main channel and porous network. Although there should be scattered arc lamp beam all over the device, but its intensity is much weaker than the focused affected zone. Bacterial movement in the main channel and porous network was actually examined in bright field, and the motility was not affected at all.



Figure E.4 Affected zone (the green circle) by arc lamp light beam on the H-µChip.

## E.5 GFP Transformation to P. putida

Besides the *E. coli* strains, GFP transformation was tried in *P. putida* strains too. The protocol was the same as stated in the Bio-Rad pGLO bacterial transformation kit. Generally, a pGLO plasmid containg the genes for expressing both GFP and ampicillin resistence were shot into the cell body by heat shcok. However, the plasmid transformation was not successful due to the biological stress inside the *P. putida* bacterium. Dr. Joshua Shrout tried to tag these strains chromosomally with a Tn7 transposon insert at the site adjacent to the gene glmS on the *Pseudomonas* chromosome. The details of this transformation were well documented by Schweizer's group at Colorado State (Hoang et al., 1998). Genes of antibiotic selection was also tagged into the bacterial chromosome, but they were not required to maintain fluorescence and/or prevent loss; they were required for conjugation. In this case, both *P. putida* F1 and CheA mutant were tagged with GFP and kanamycin-streptomycin resistant; another CheA

Both the chemotactic and nonchemotactic *P. putida* strains successfully expressed GFP after the inoculation in the modified Hutner's Mineral Base, which was mentioned in Chapter 3. However, the GFP expression was not strong compared to that in *E. coli* strains, and only about one third of the overall bacterial population showed the fluorescence, even with the selective help of corresponding antibiotic addition. More critically, the GFP labeled *P. putida* strains became less motile, or almost non-motile under both the bright field and fluorescence observation. Thus, more work needed to be done to improve the fluorescence quality, as well as to maintain the motility of GFP labeled *P. putida*, and it would be worthwhile to use them in many different circumstances in future research.

#### E.6 Simulated Flow Patterns in the µChips

Both the convection free gradient generator (CF- $\mu$ Chip) and the heterogeneous microfluidics (H- $\mu$ Chip) involved with injection flows to achieve their functions. H- $\mu$ Chip studied the impact of flow rates on bacterial distribution in the microfluidic device; the main function of CF- $\mu$ Chip was to study bacterial chemotaxis in a no-flow condition, but the no-flow environment was achieved by the two balanced flow streams in the upper channel. Thus, it was important to understand the flow patterns in the microfluidic devices at the first step. The flow patterns were hard to illustrate directly by experimental methods, so a finite-element solver COMSOL 4.3 was used to solve the two dimensional Navier-Stokes equation and the Advection and Diffusion equations.

### <u>E.6.1 CF-µChip</u>

As mentioned in Chapter 3 and illustrated by Figure 3.4, bacteria suspension and chemical solution were injected from two parallel and symmetric inlets, and the injection velocity was comparable to 0.38 mm/s in the top channel. Figure E.5 shows how the velocity field distributes in the top channel, as the velocity at the centerline is about 1.5 times larger than the average velocity of 0.38 mm/s, and the velocity reduces to zero at the sidewalls due to the no slip condition. More importantly, the velocity field can be used to examine the mass transfer between the streams of bacteria and chemical.



**Figure E.5** Simulated velocity field in the top channel of the CF- $\mu$ Chip. Colors toward the red end of the legend bar mean higher values, and colors toward the blue end mean lower values. The black arrows represent the approximate vectors of velocity at certain locations.

*P. putida* and toluene system was tested first for their distribution under the flow rate (no chemotaxis), and the simulated results were indicated by Figure E.6 and E.7. The bacterial random motility is  $1.6 \times 10^{-9}$  m<sup>2</sup>/s for *P. putida* (Wang and Ford, 2009) and attractant diffusion coefficient is  $9.5 \times 10^{-10}$  m<sup>2</sup>/s for toluene (Montgomery, 1996). Toluene was injected from the upper left inlet, and *P. putida* from the lower left inlet, and they gradually diffused into each other as the flow moved along the channel.



**Figure E.6** Simulated distribution of toluene solution in the top channel of the CF- $\mu$ Chip. Colors toward the red end of the legend bar mean higher values, and colors toward the blue end mean lower values. The rainbow color in the middle of the channel means the diffusion zone. The eight black circles indicate the sizes and locations of the vias for the cross channels in the bottom layer.



**Figure E.7** Simulated distribution of *P. putida* suspension in the top channel of the CF- $\mu$ Chip. Colors toward the red end of the legend bar mean higher values, and colors toward the blue end mean lower values. The rainbow color in the middle of the channel means the diffusion zone. The eight black circles indicate the sizes and locations of the vias for the cross channels in the bottom layer.

The diffusing zones indicated from the figures above were expected not to interfere with the vias locating besides the sidewalls. The simulated data of transverse distribution for bacteria and chemical were collected at the outlet on the right side of the channel, and the distribution curves were plotted in Figure E.8. The x-axis stands for the different location points along the transverse direction of the 3 mm wide channel.



**Figure E.8** Simulated distribution of both bacteria and chemical on the transverse direction at the outlet of the top channel. (a) is for *P. putida* with toluene and (b) is for *E. coli* with  $\alpha$ -methylaspartate ( $\alpha$ -mASP).

*E. coli* and  $\alpha$ -mASP system was also checked the same simulation procedure, and the results were similar to *P. putida* and toluene, except their diffusion zone was a bit narrower than the other pair. The bacterial random motility is  $3.0 \times 10^{-10}$  m<sup>2</sup>/s for *E. coli* HCB1 and attractant diffusion coefficient is  $8.6 \times 10^{-10}$  m<sup>2</sup>/s for  $\alpha$ -mASP (Long and Ford, 2009). In either situation, the diffusion zone does not interfere with the vias, because the diameter of via is 600 µm, so the vias are within the unshaded region (Figure E.8) and should be able to maintain pure solution/suspension concentration.

#### <u>E.6.2</u> H-µChip

The flow pattern is simulated in the heterogeneous microfluidic structure at different flow rates, as shown in Figure E.9 and E.10. The blue square area stands for the porous matrix with proper values of permeability and porosity, which are within the typical range for contaminant layers composed of sand and gravel. The values of permeability and porosity are listed in Table 6.1. The flow in the porous matrix is fairly

small compared to the major flow in the horizontal channel under either 0.25 or 5 m/d. These simulation results on flow patterns revealed an expected flow environment, where the major bulk fluid flowed in the highly permeable horizontal channel, and only a small portion of flow distributed in the porous region with less permeability. However, the study would show that the small portion of flow could also deliver bacteria to the whole porous matrix and it also helped chemotactic bacteria stay longer in this region in presence of NAPL attractant ganglia.



**Figure E.9** The simulated flow pattern at 0.25 m/d in the H- $\mu$ Chip. Colors toward the red end of the legend bar mean higher values, and colors toward the blue end mean lower values. The black arrows represent the approximate vectors of velocity at certain locations.



**Figure E.10** The simulated flow pattern at 5.0 m/d in the H- $\mu$ Chip. Colors toward the red end of the legend bar mean higher values, and colors toward the blue end mean lower values. The black arrows represent the approximate vectors of velocity at certain locations.