

# **Toward Robotic Triage: A Distributed Task and Motion Planning Framework for Efficient Human-Robot Emergency Response**

A Technical Report submitted to the Department of Systems Engineering

Presented to the Faculty of the School of Engineering and Applied Science  
University of Virginia • Charlottesville, Virginia

In Partial Fulfillment of the Requirements for the Degree  
Bachelor of Science, School of Engineering

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Spring 2025

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On my honor as a University Student, I have neither given nor received unauthorized aid on this assignment as defined by the Honor Guidelines for Thesis-Related Assignments

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